

# ENABLING THE NEXT LEVEL OF AUTONOMOUS DRIVING WITH ADVANCED OBJECT GENERATION

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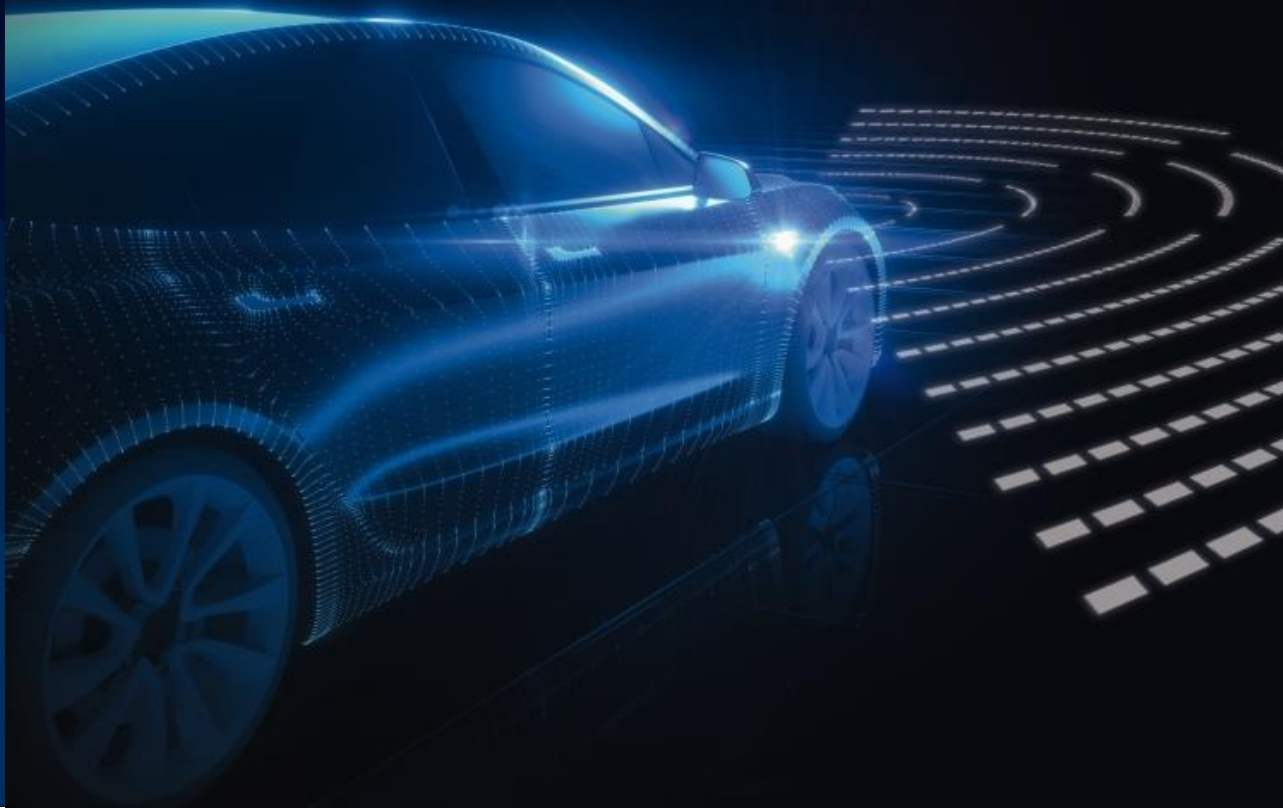
**ROHDE & SCHWARZ**

Make ideas real



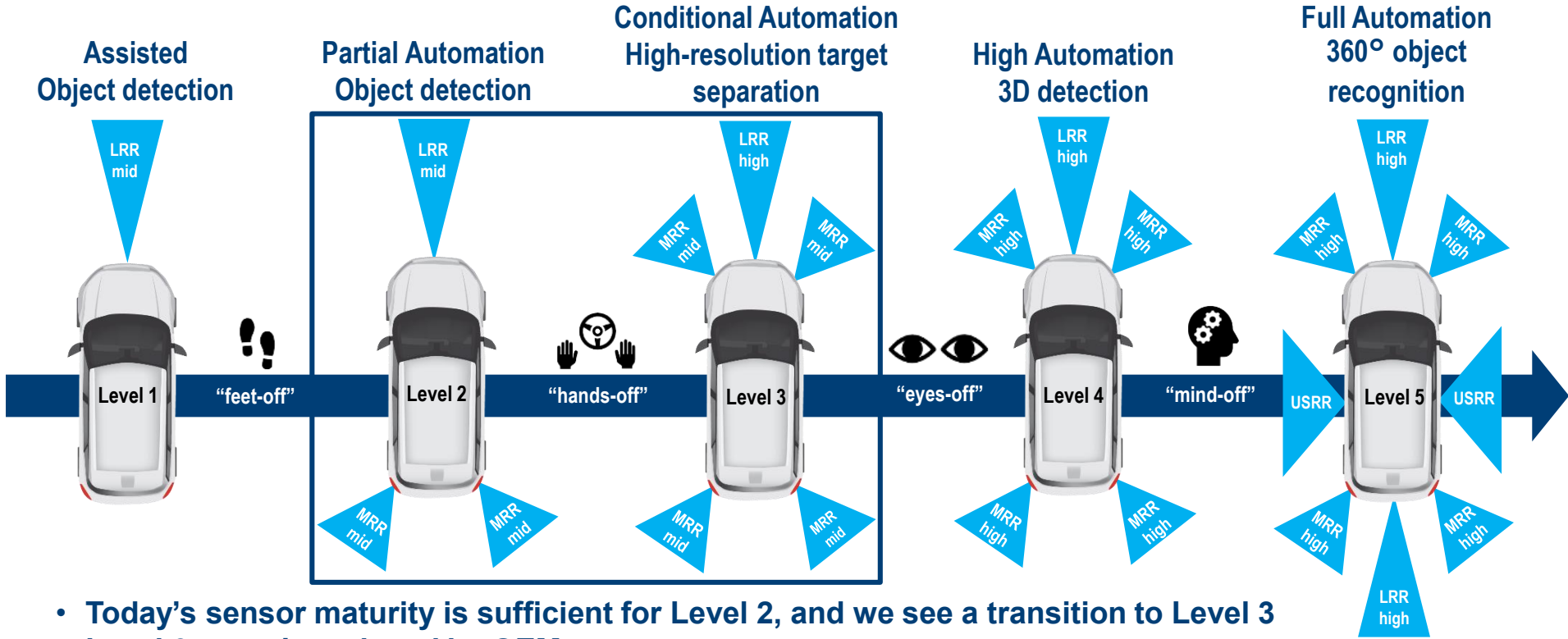
# AGENDA

- ▶ **Automotive radar technology and market update**
- ▶ QAT100 Electronically steerable antenna array
- ▶ AREG800A advanced automotive radar echo generator
- ▶ Applications and solutions
- ▶ Automotive radar testing product portfolio
- ▶ Summary and learnings



# RADAR BASED AUTONOMOUS DRIVING

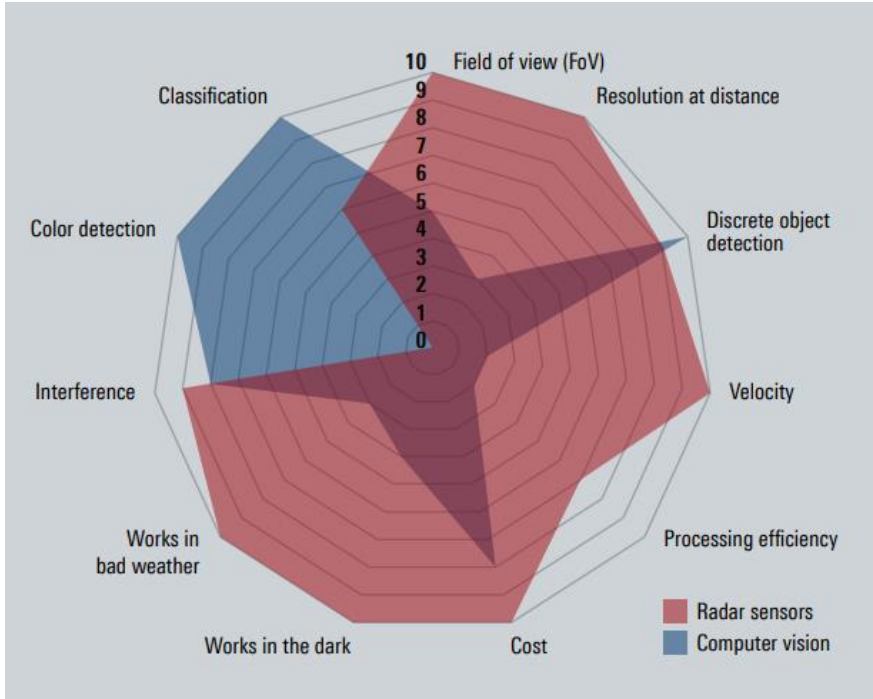
## AUTOMOTIVE RADAR EVOLUTION



- Today's sensor maturity is sufficient for Level 2, and we see a transition to Level 3
- Level 2+ was introduced by OEMs

# RADAR BEING PART OF SENSOR FUSION

## PILLAR OF AUTONOMOUS DRIVING



### Strengths of Radar Sensors versus other ADAS Sensors

- Instantaneous measurement of distance, vertical angle, horizontal angle and velocity (4D)
- Works in the dark and with adverse conditions such as smoke, fog and dust
- Combines well with camera in redundant systems due to different operating frequencies
- Cost efficient due to high volume and market penetration
- Radar still has strong innovation potential towards imaging radar

# RADAR TECHNOLOGY TRENDS

## TYPICAL SENSOR PARAMETERS

Radar Module Parameters	Short-Range Radar	Standard Mid-Range Radar	Premium Mid-Range Radar	Standard Long-Range Radar	Premium Long-Range Radar	Imaging Radar
Frequency Range [GHz]	24,76-77,77-81	76-77	77-81	76-77	76-77	76-81
Typical Bandwidth [MHz]	200, 1000, 4000	1000	2000	500	1000	2000
Range [m]	80	150	150	250	300	300
Range Resolution [cm]	300, 30, 3.5	30	7.5	75	30	60, 9.5
FOV Azimuth / Elevation [°]	±60 / ±0	±30 / ±0	±50 / ±15	±15 / ±5	±15 / ±10	±50 / ±15
Typical Channel Number [Transmit / Receive]	3 TX / 4 RX	4 TX / 8 RX	8 TX / 12 RX	4 TX / 8 RX	12 TX / 16 RX	48 TX / 48 RX

*(Data sheet values of commercially available sensors from various suppliers)*

# RADAR TECHNOLOGY TRENDS

## Technology Trends



- **5/6<sup>th</sup> generation radar sensors dominate the market**
- **Single Chip CMOS with 5 GHz bandwidth and more complex modulation**
- **High priority on interference mitigation**
- **Radar antenna aperture is increasing**
- **Very short distance object simulation required during radar sensor R&D and validation**
- **Need for complex moving object scenarios to be emulated in a lab environment is increasing**
- **OEMs want an improved test coverage:**
  - **Scenario validation (HIL, VIL)**
  - **Electromagnetic susceptibility testing**
- **AI will improve object detection and tracking capabilities**

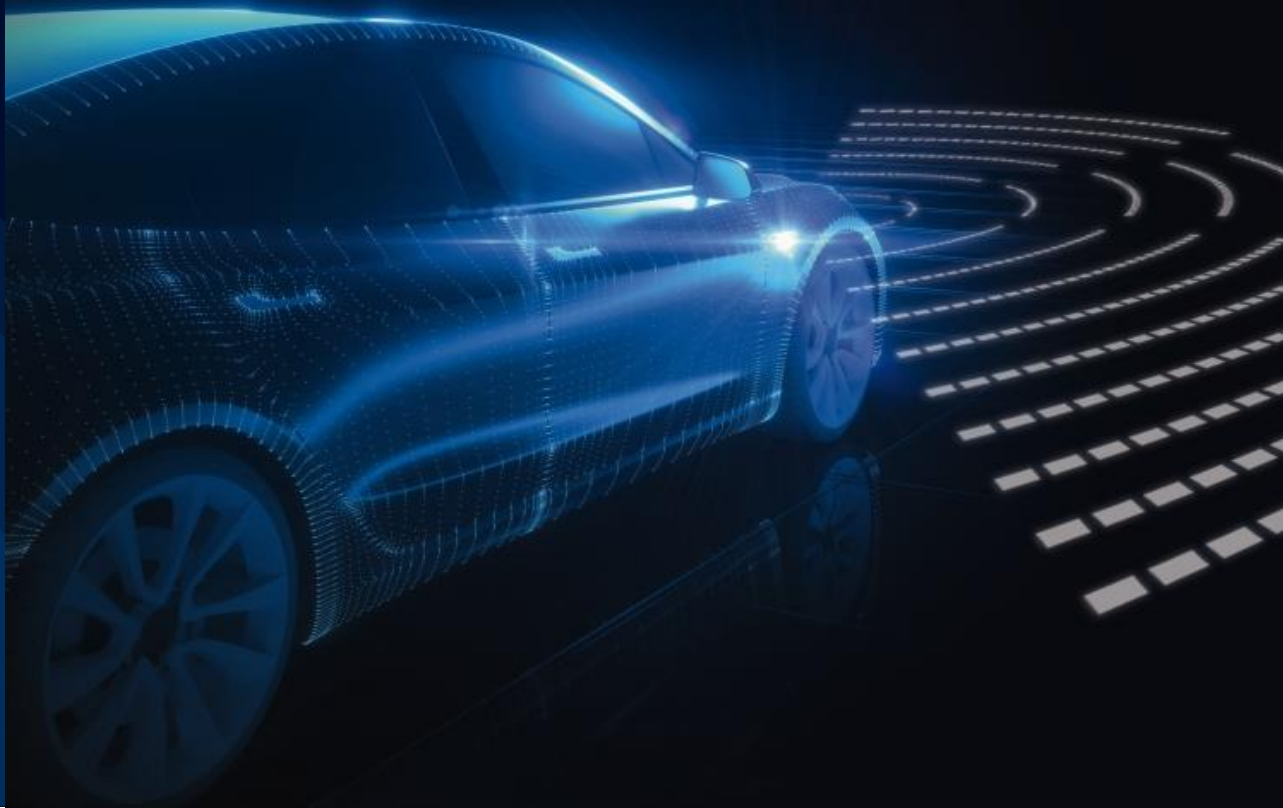
## Business Trends



- **Highly dynamic radar chip supply chain**
  - **Large TIER1s develop own chips**
  - **New Asian suppliers for mainstream ICs**
- **Imaging radar takes off, and 30% market share is expected in 2027**
- **Radar sensor market is growing with 13%.**
- **Many new players in the radar supply chain**

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# ADVANTAGES

## R&S®QAT100 VS. MECHANICAL APPROACH



No mechanical movement

OTA radar stimulation with azimuth simulation without needing to physically move antennas:

- Less wear and tear
- Better RF performance
- No mechanical handovers required



Immune to vibration

Perfectly fitted for ViL testbed mounting:

- Reduced amount of RF connections
- Reliable due to vibration robust design



Precise and repeatable

96 TX antennas guarantee a precise and repeatable azimuth simulation without the need of physical movement:

- High precision
- Great repeatability
- High resolution



Scalable solution

Several Frontends can be stacked to simulate up to 360° of radar environment.

- Highly flexible and ready for expansion
- Radar FOV of several sensors can be simulated by one or multiple frontends



Clean RF - no reflections from FE

The PCB antennas have a much lower RCS as the standard gain horns used in other systems.

Together with the QAT-B50 shielding system, a shielded RF environment can be guaranteed

- Reliable operation
- Reduced influence of other T&M equipment
- No testbed mode required for the radar





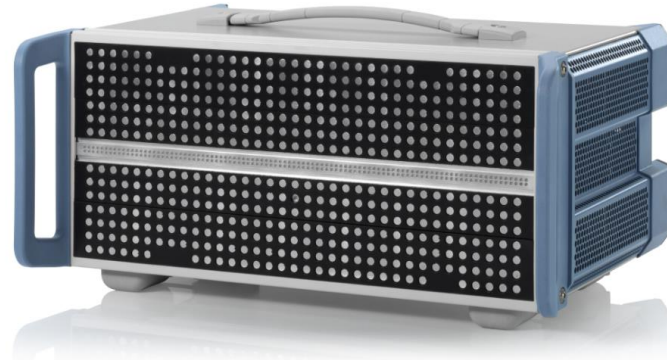
# R&S® QAT100

## FRONTEND VERSIONS



### R&S® QAT100 with QAT-B11 (SIMO) frontend

- 96 transmit & 5 receive antennas
- Optional second independent TRX line
- Simulation of up to 8 echoes from different directions



### R&S® QAT100 with QAT-B21 (MIMO) frontend

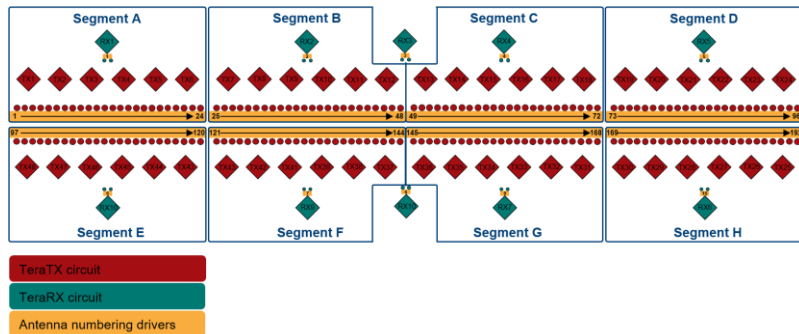
- 96 transmit / receive antenna pairs
- Optimized for MIMO technology
- Simulation of up to 4 echoes from different directions



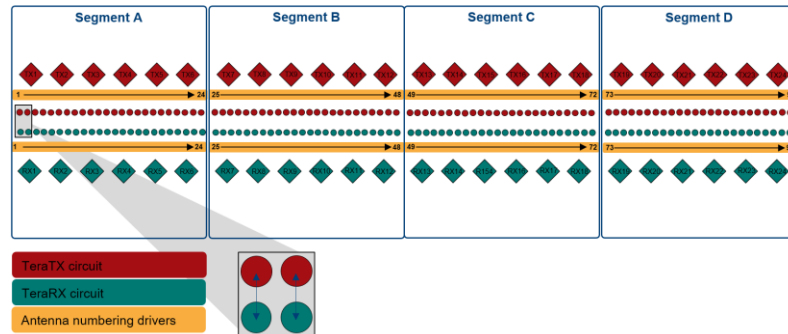
# R&S® QAT100

## FRONTEND VERSIONS

### R&S® QAT100 QAT-B11 / -B2 ANTENNA NUMBERING



### R&S® QAT100 QAT-B21 ANTENNA NUMBERING



### R&S® QAT100 with QAT-B11 (SIMO) frontend

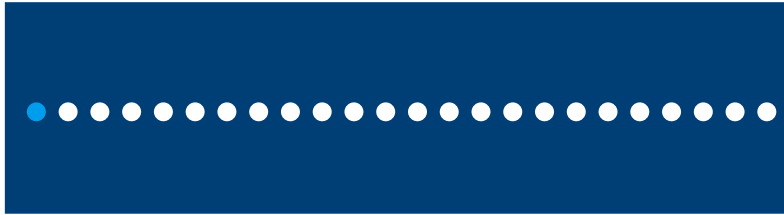
- 96 transmit & 5 receive antennas
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- Simulation of up to 8 echoes from different directions

### R&S® QAT100 with QAT-B21 (MIMO) frontend

- 96 transmit / receive antenna pairs
- Optimized for MIMO technology
- Simulation of up to 4 echoes from different directions

# R&S®QAT100 WITH QAT-B21

Segment #1

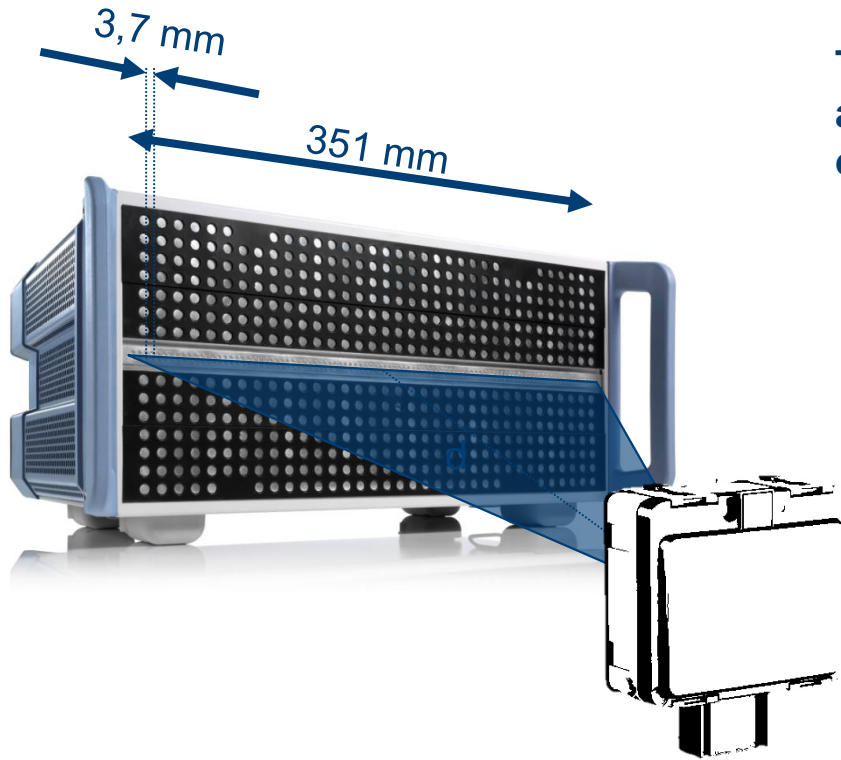


Segment #2



- **Segment mode still available**
- **Intersecting targets only at certain positions**

# FIELD-OF-VIEW & ANGULAR RESOLUTION



The field-of-view (FOV) and angular resolution achievable with the R&S®QAT100 are dependent on the setup but can be calculated as follows:

**Field-of-view:**

$$\alpha = 2 \cdot \tan^{-1} \left( \frac{351 \text{ mm}}{d} \right)$$

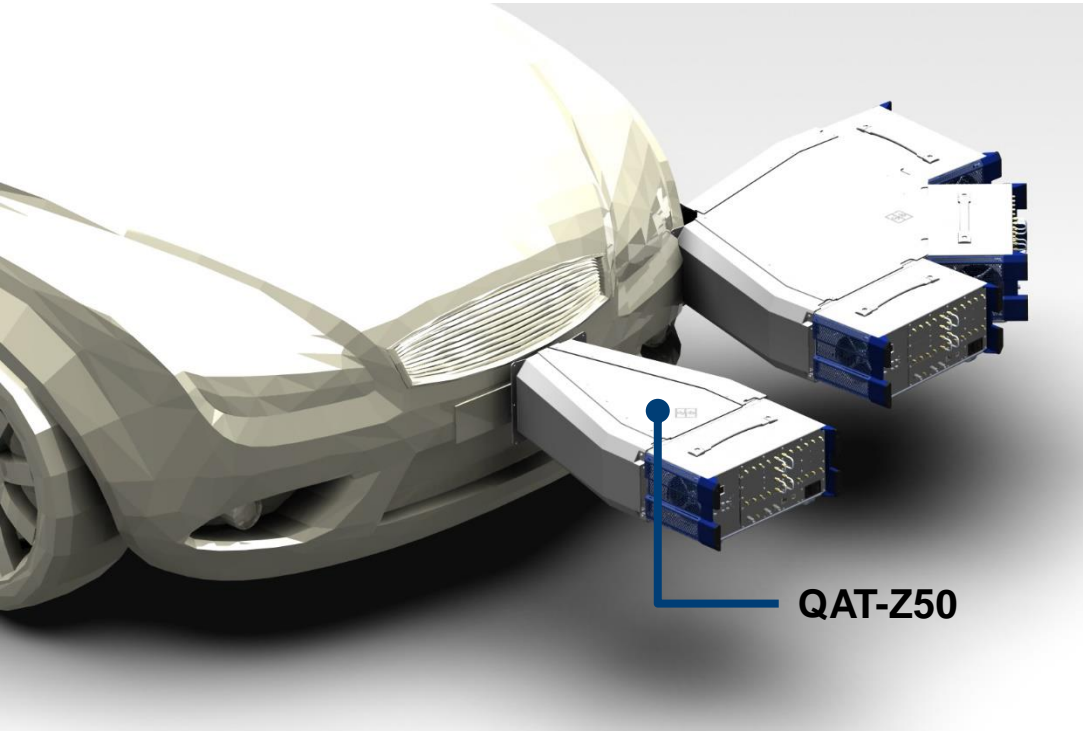
**Angular resolution:**

$$\Delta\alpha = \tan^{-1} \left( \frac{3.7 \text{ mm}}{d} \right)$$

Distance (d)	Field-of-view ( $\alpha$ )	resolution ( $\Delta\alpha$ )
500 mm	38.7°	0.42°
700 mm	28.1°	0.30°
1000 mm	19.9°	0.21°
1500 mm	13.34°	0.14°
2100 mm	10.0°	0.10°

# R&S® QAT100 ADVANCED ANTENNA ARRAY

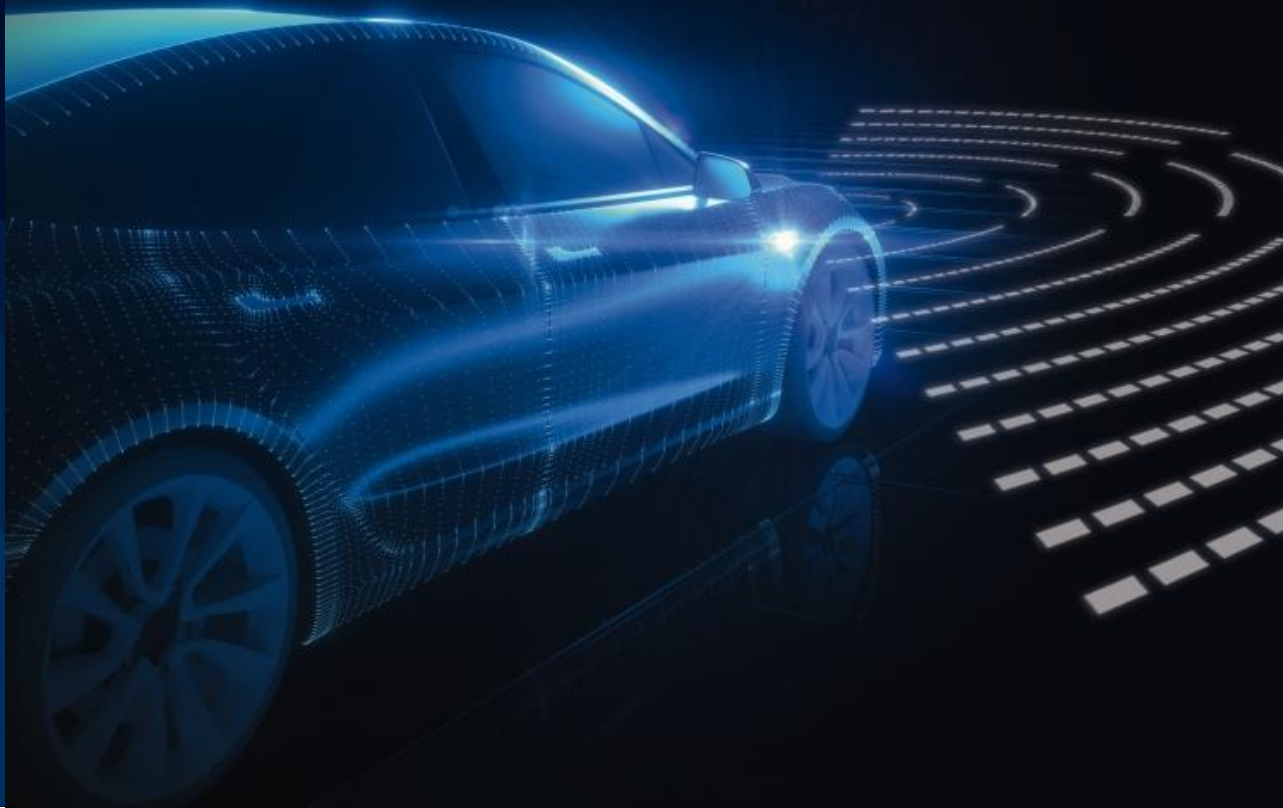
## QAT-Z50 SHIELDING SYSTEM



- **QAT-Z50 shielding system**
  - 50 cm long, 10° opening
  - Direct mounting kit for QAT
- **Challenges**
  - Car mounting kit respectively QAT stand in front of car
  - Customization based on e.g. CAD required


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# R&S® AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

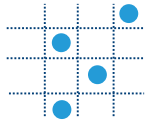
MODERN TEST SETUP CORE ELEMENT. R&S® AREG800A UNIQUE FEATURES FOR THE BACKEND



Generation of dynamic objects



Extremely short object distances




Multiple independent objects



Synchronization of multiple QATs and AREG800As



High instantaneous bandwidth



Built-in real time interface



Standardized OSI (Open Simulation Interface) HIL Interface



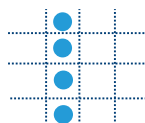
Fully harmonized with frontend



Scalable solution

# R&S®AREG8-81S/D MMW FRONTEND

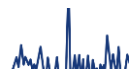
## UNIQUE FEATURES FOR THE AREG FRONTEND



Multiple objects  
with the same direction  
and independent RCS,  
range and doppler



Suitable for MIMO Radars  
Common RX/TX antenna  
and integrated circulator



SNR performance  
RCS accuracy



High instantaneous  
bandwidth



Short artificial object  
distances



Precise and  
repeatable



Scalable solution

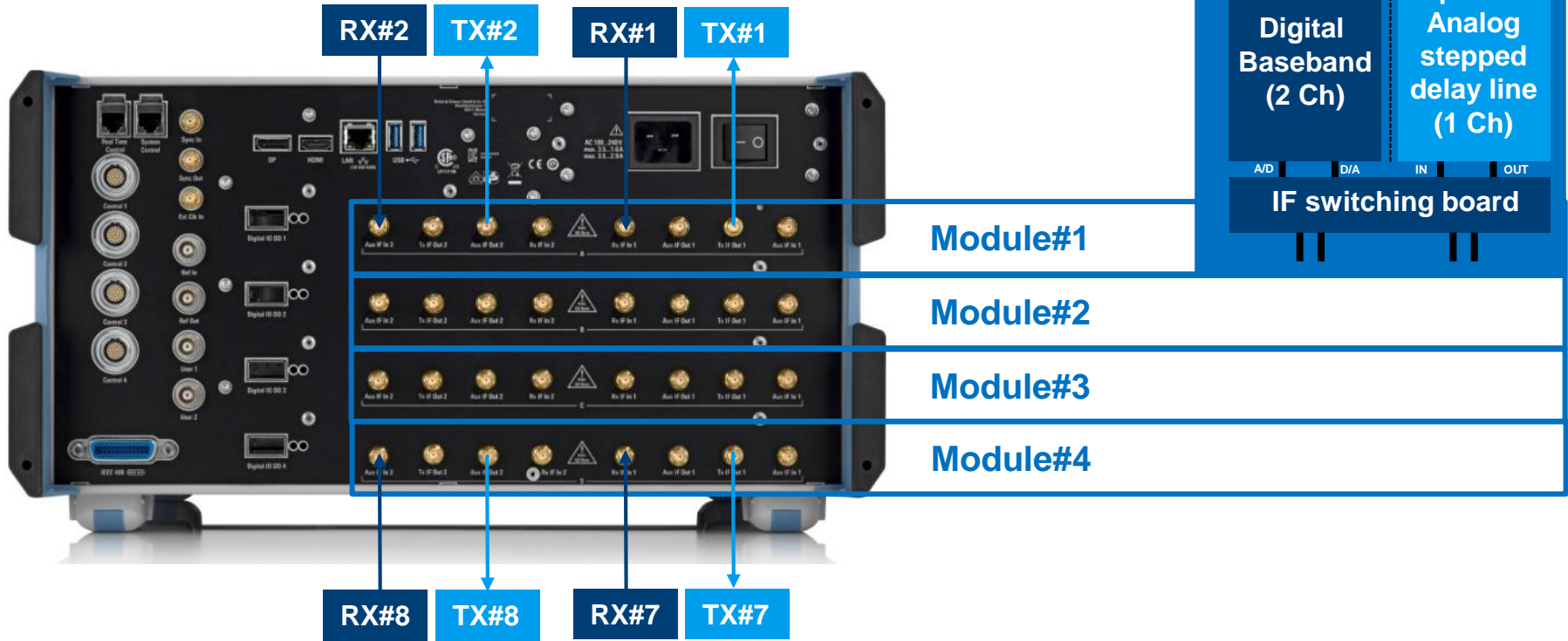


Suitable for EMC environments



# R&S®AREG800A SCALABILITY, FLEXIBILITY AND MODULARITY

## GROWS WITH YOUR NEEDS

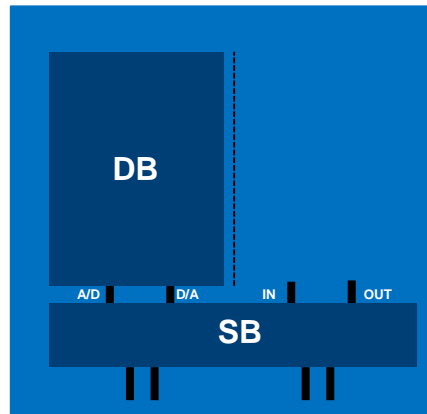


# R&S®AREG800A SCALABILITY, FLEXIBILITY AND MODULARITY

## MODULAR CONCEPT

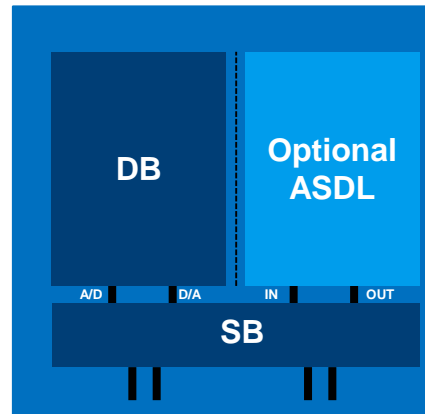
- The Digital Board (DB), the IF Switching Board (SB) and the optional Analog Stepped Delay Line Board (ASDL) are forming the smallest backend module
- A module has one (for 5GHz bandwidth) or two (for 2GHz bandwidth) IF paths, each with individual A/D and D/A conversion

### Digital Concept

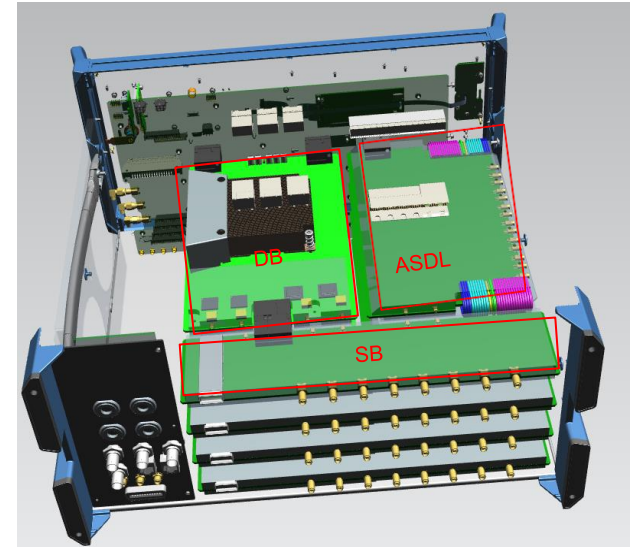


Range: <17 m to 3000 m

### Hybrid Concept: Digital + Analog




Range: <4 m to 3000 m



# R&S®AREG800A ALLOWS EXTREMELY CLOSE OBJECT DISTANCE FOR FMCW RADARS

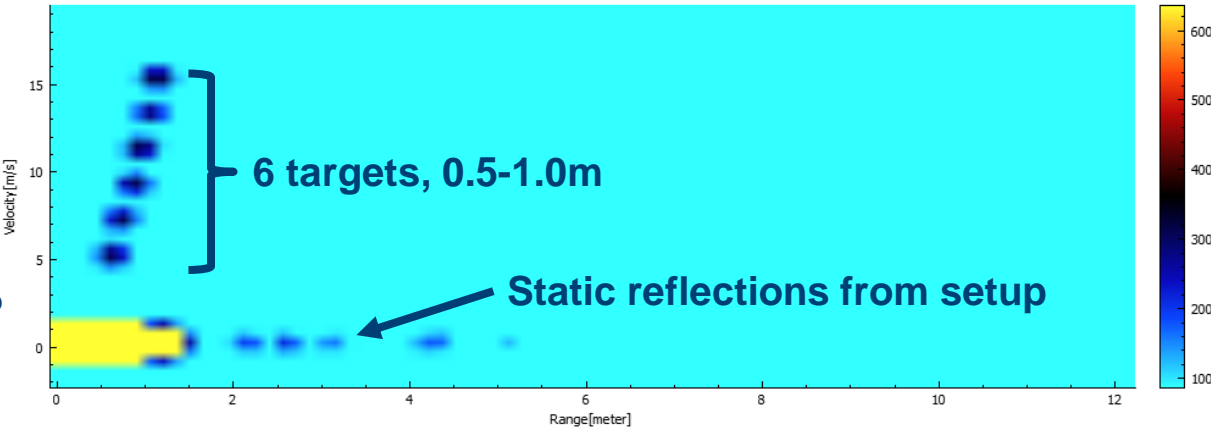
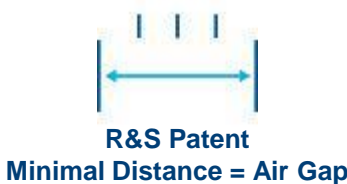
FULL DIGITAL IMPLEMENTATION. HYBRID OBJECT GENERATION IS STILL POSSIBLE

- Up to 4 channels with up to 8 targets per channel
- Minimum distance  $\geq$  air gap value of the radar under test
- Example below with a Tier 2 DUT



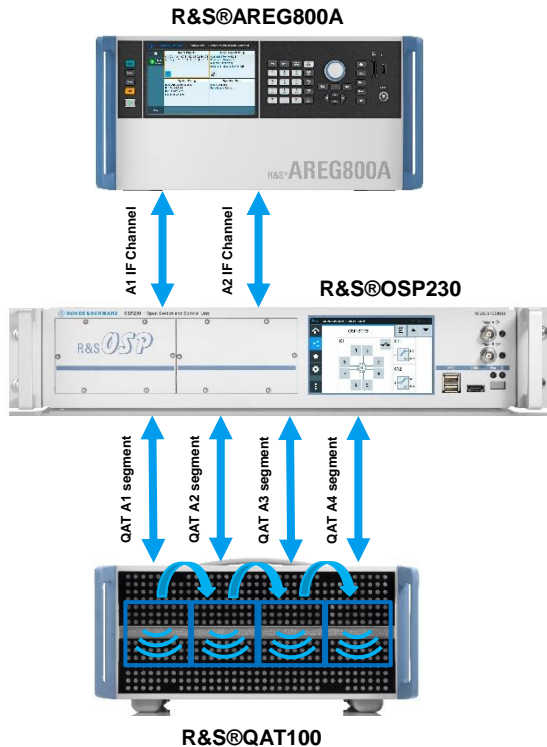
Object	Status	Range (m)	Attenuation (dB)	Doppler Speed (m/s)	Horizontal Angle (deg)	RCS (dBm²)
1	On	0.50	0.00	5.000 0	0.0	-59.1
2	On	0.60	0.00	7.000 0	0.0	-56.0
3	On	0.70	0.00	9.000 0	0.0	-53.3
4	On	0.80	0.00	11.000 0	0.0	-51.0
5	On	0.90	0.00	13.000 0	0.0	-48.9

Doppler Heatmap

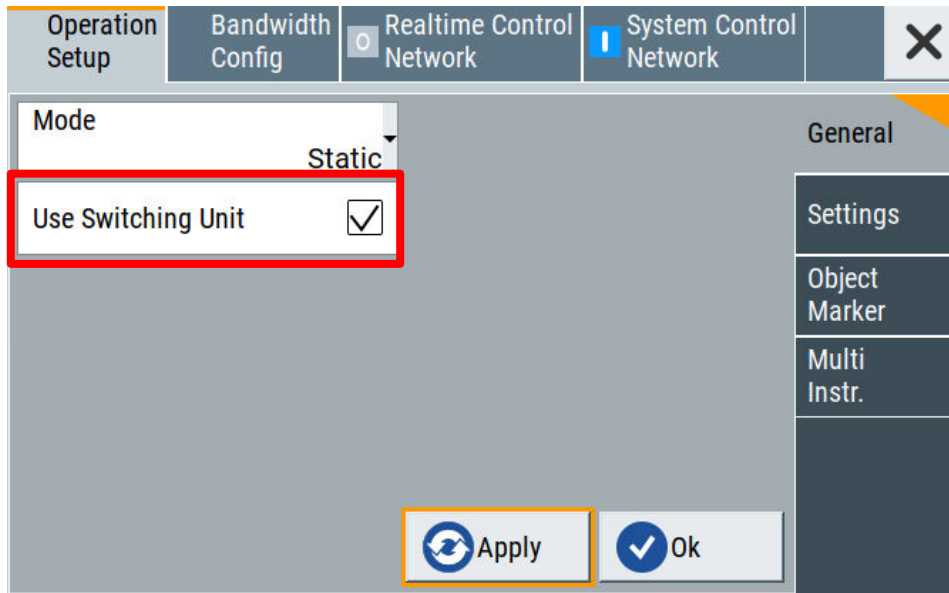


# R&S®AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

## OSP Integration

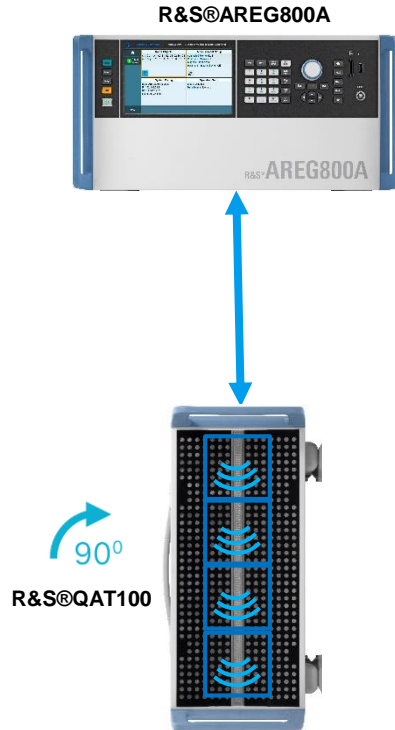


Use less channels in the R&S®AREG800A than in the R&S®QAT100 and control the whole FOV of the frontend

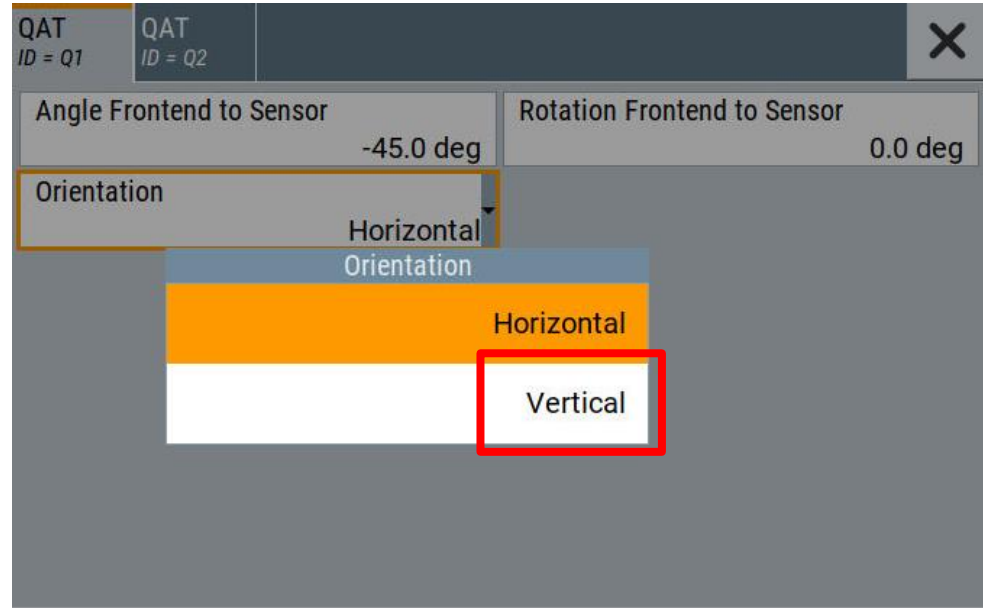


# R&S®AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

## Elevation Angle Support

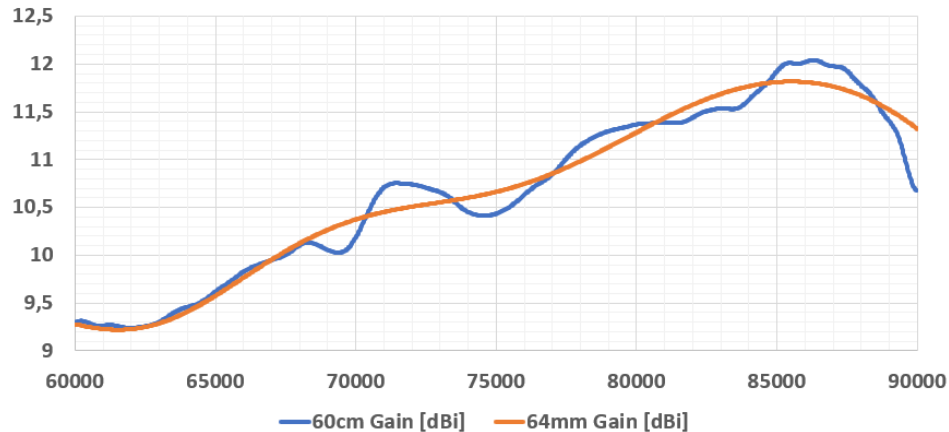


## Elevation angle simulation capability



# R&S®AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

## Improved mmW TRX FE Antenna Characterization



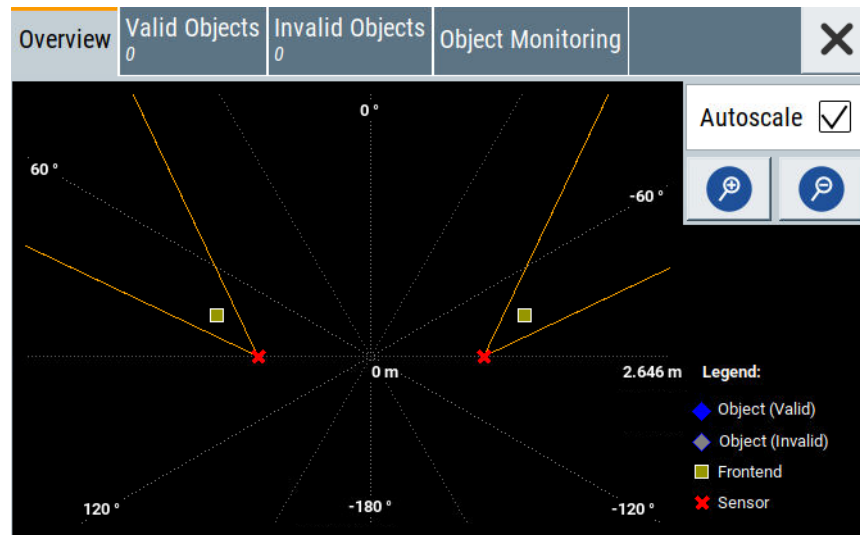
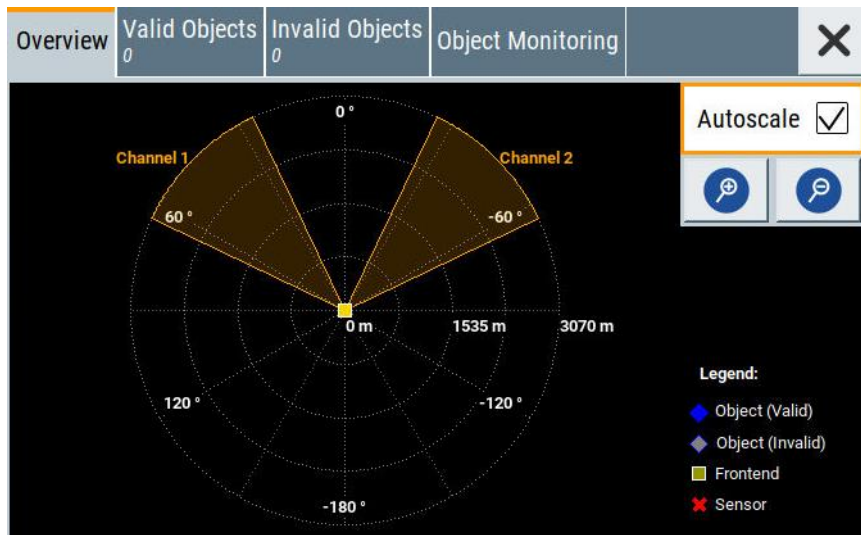
The screenshot shows the software configuration window for the AREG800A. The 'Antenna Gain' section is highlighted with a red box, and the 'Antenna Gain List ...' option is highlighted with a yellow box. Other visible settings include:

- Air Gap: 50 cm
- Frontend Bandwidth: 4.00 GHz
- Frontend Center Frequency: 76.0 GHz
- Frontend Serial Number: 100000
- Frontend Type: AREG8-81S
- Power Sensor: No Sensor

Increase the accuracy of your measurement

# R&S®AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

## Improved calculations for overview geometrical distance-angle



Define a digital twin of your physical setup and test more than 1 radar at the same time

# R&S®AREG800A AUTOMOTIVE RADAR ECHO GENERATOR



## gPTP for HiL

The screenshot shows the 'Date / Time' configuration window. The 'Time Protocol' dropdown menu is open, displaying three options: 'None', 'NTP', and 'gPTP'. The 'gPTP' option is highlighted with a red rectangular box. The background window shows the date set to 2023-05-10 and the time set to 15:45:32.

System time synchronization using the  
generic precision time protocol

## Adjustable speed of light

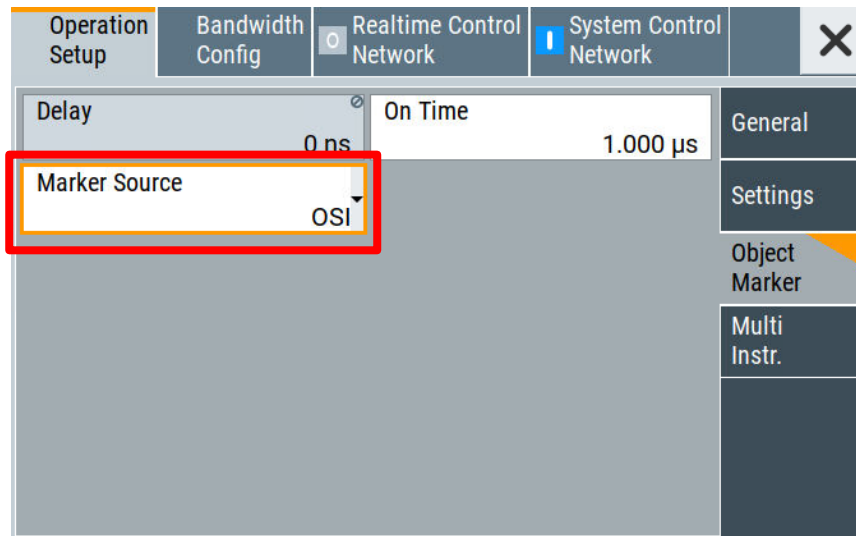
The screenshot shows the 'Units' configuration window. The 'Speed of Light' field is highlighted with a red rectangular box. The field displays the value '299 792 458 m/s'. Below the field, the minimum and maximum values are shown: 'Min = 200 000 000 m/s' and 'Max = 300 000 000 m/s'. The field also has a dropdown menu with options: 'm/s', 'km/h', and 'mph'.

Fit the radar sensor design and increase  
the accuracy of your measurement



# R&S®AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

## Command output signal to trigger external devices



Increase the capability of your measurement setup in HiL mode

# R&S®AREG800A IS HARMONIZED WITH THE FRONTENDS

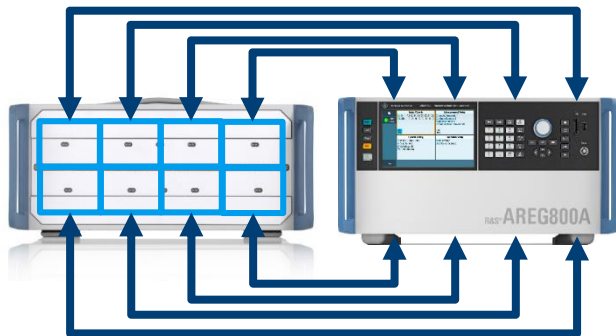
## SIGNAL DISTRIBUTION OVERVIEW

**A – One QAT100 and one AREG800A**  
For simulation of dense scenarios

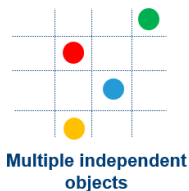
Up to 8 objects

IF#1 to IF#4

IF#5 to IF#8

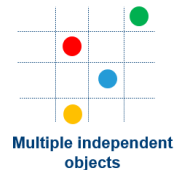
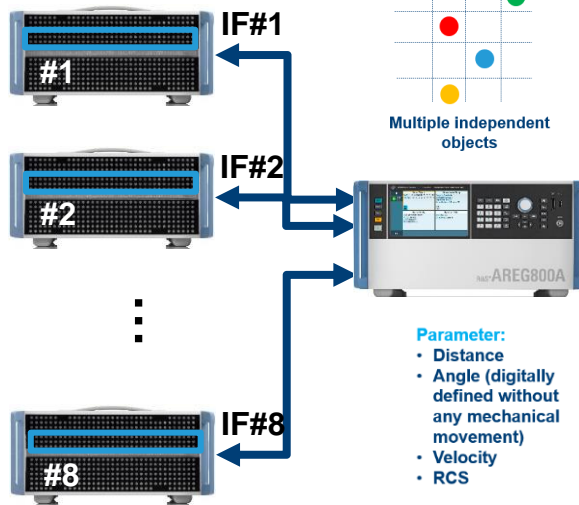


- Parameter:**
- Distance
  - Angle (digitally defined without any mechanical movement)
  - Velocity
  - RCS



**B – Multiple QAT100s and one AREG800A**  
For covering wide Field-of-VIEWS

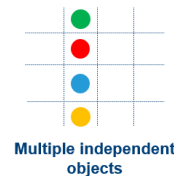
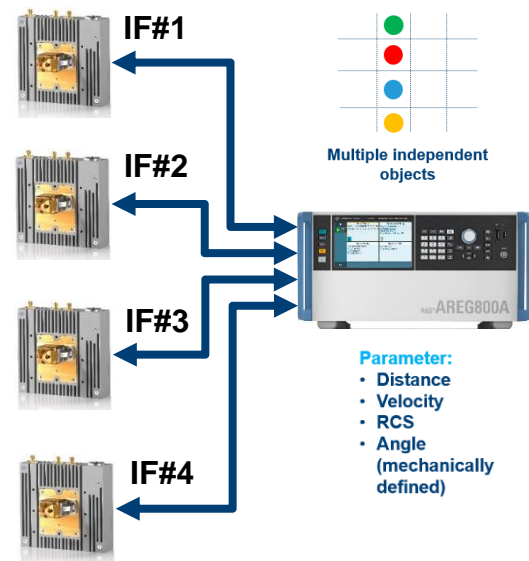
Up to 8 objects



- Parameter:**
- Distance
  - Angle (digitally defined without any mechanical movement)
  - Velocity
  - RCS

**C – mmW Frontends and AREG800A**  
For performance test cases

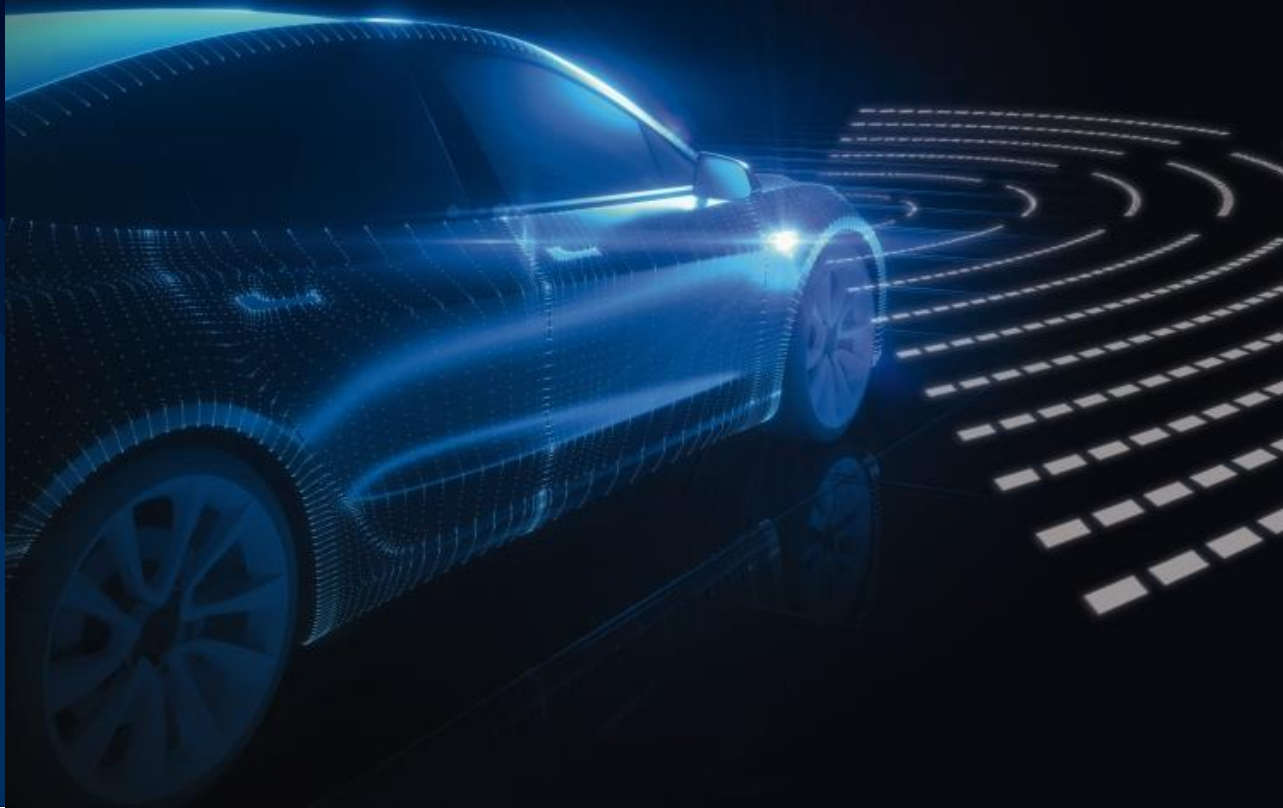
Up to 32 objects



- Parameter:**
- Distance
  - Velocity
  - RCS
  - Angle (mechanically defined)

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# R&S®AREG800A AUTOMOTIVE RADAR ECHO GENERATOR

APPLICATIONS AND SOLUTIONS – ALL IN ONE FOR AUTOMOTIVE RADAR TESTING

## EOL Production Test and Calibration



R&S®AREG100A or R&S®AREG800A

## Research and Development



R&S®AREG800A with various frontends

## Hardware-in-the-Loop



R&S®AREG800A and R&S®QAT100

## Vehicle-in-the-Loop (together with AVL)



R&S®AREG800A and R&S®QAT100

# RADAR MODULE PRODUCTION TESTER FOR TIER 1

PARTNERSHIP WITH NOFFZ TECHNOLOGIES

- Generate echoes with defined Doppler, RCS and Range
- Perform radar sensor calibration
- Future-proof CATR reflector technology for growing antenna apertures
- Seamless CATR production tester solution for developing radar in ATS1500C
- Combine CATR and AREG ensures best quiet zone



# AUTOMOTIVE RADAR VALIDATION IN EMC ENVIRONMENTS

## AREG800A AND AREG MMW FRONTENDS ARE SUITABLE FOR TESTING RADARS IN COMPREHENSIVE AND DYNAMIC EMC ENVIRONMENTS

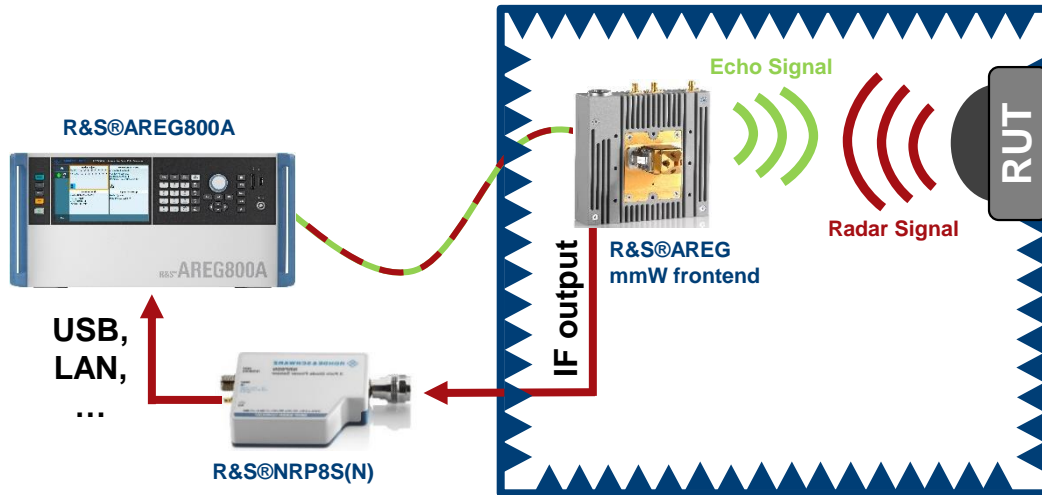


- Testing of radar operation under EMC stress
- Simulation of driving scenarios using R&S®AREG800A

# MEASURE THE SENSOR'S TRANSMITTED POWER AND EIRP

## COMPLY TO THE RADIO EQUIPMENT DIRECTIVE AND EXPLOIT THE MAXIMUM EIRP

R&S@ATS1500C



- Connect a power sensor with upper frequency limit of 6 GHz
- Receive path from frontend to IF output port is calibrated
- Read the measured EIRP of the radar sensor directly on the GUI of the AREG base unit

# HIGH SENSITIVITY SIGNAL ANALYSIS MEASUREMENTS

## COMPREHENSIVE RADAR SIGNAL ANALYSIS

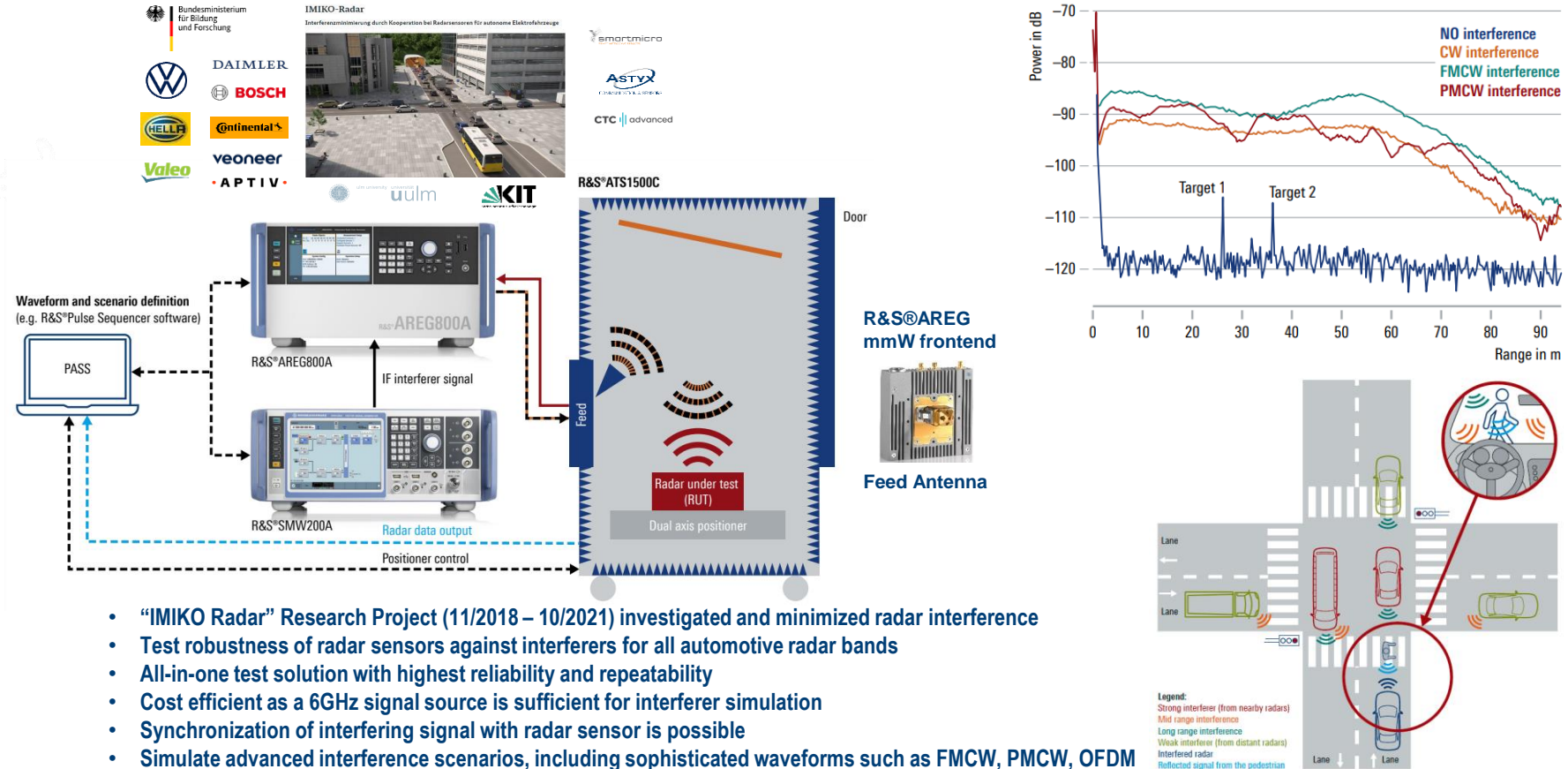


- Measuring frequency linearity, length, long-term stability and power of chirp to improve accuracy and fulfill regulatory requirements
- Measuring phase noise to increase sensitivity



# AUTOMOTIVE RADAR CONFORMANCE TESTING

## TEST THE RADAR INTERFERENCE MITIGATION ALGORITHM PERFORMANCE

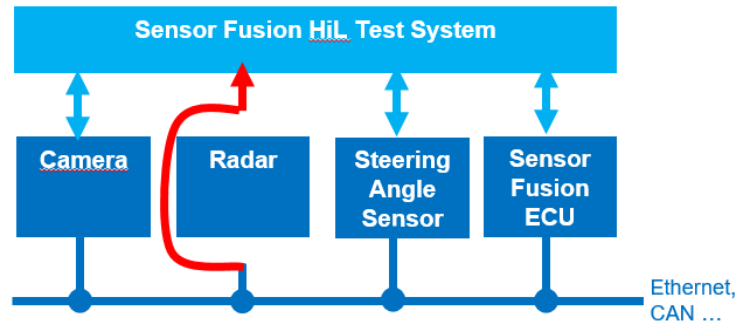


- “IMIKO Radar” Research Project (11/2018 – 10/2021) investigated and minimized radar interference
- Test robustness of radar sensors against interferers for all automotive radar bands
- All-in-one test solution with highest reliability and repeatability
- Cost efficient as a 6GHz signal source is sufficient for interferer simulation
- Synchronization of interfering signal with radar sensor is possible
- Simulate advanced interference scenarios, including sophisticated waveforms such as FMCW, PMCW, OFDM

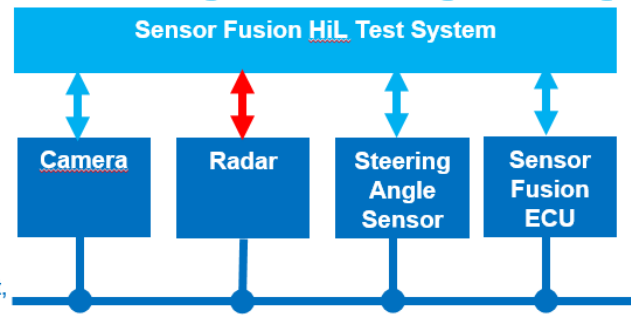
# OBJECT SIMULATION FOR HiL AND ViL TEST SYSTEMS

- New radar sensors based on SoCs require over-the-air stimulated black box testing
- NCAP will require increased testing of radars not only on the road and proving grounds, but also on the rig (vehicle-in-the-loop ViL) and in the lab (hardware-in-the loop HiL)

Yesterday – object injection for the radar



Today – OTA simulation also for fast lateral & longitudinal moving radar targets



- Over-the-air stimulation of radar sensors for component and integration HiL testing
- Electrical simulation of lateral moving targets
- Simulation of longitudinal moving targets also in very low distance

# AREG800A AND QAT100 FOR SCENARIO TESTING

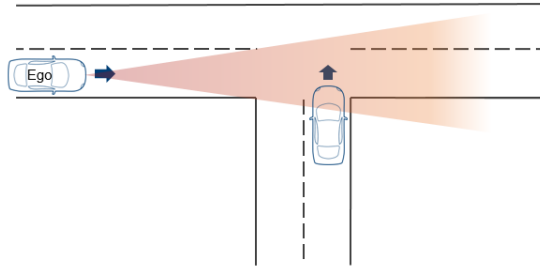
## STANDARD CONFIGURATIONS



Configuration	Targets	FOV *	Typical Use Cases
Entry	1	39°	Test of front radars in scenarios like Automatic Emergency Braking, Adaptive Cruise Control, ...
Basic	up to 2	39°	Test of front radars in scenarios like highway ALKS, country road, ...
Medium	up to 4	39°	Test of front radars in scenarios like highway ALKS, country road, ...
Advanced	up to 6	117°	Test of front and corner radars in scenarios like city thoroughfare, highway construction sites, ...
Complex	up to 8	117°	Test of front and corner radars in scenarios like urban intersections, Highway Construction sites, ...

# EXEMPLARY DRIVING SCENARIOS

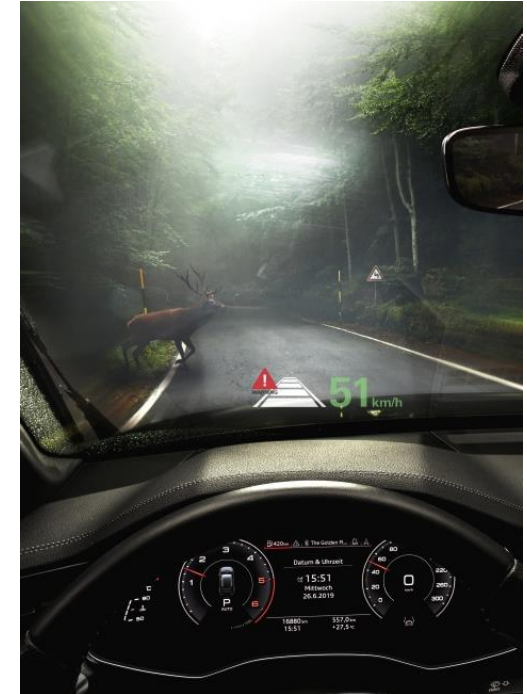
## BASIC INSTRUMENT CONFIGURATIONS



### Application:

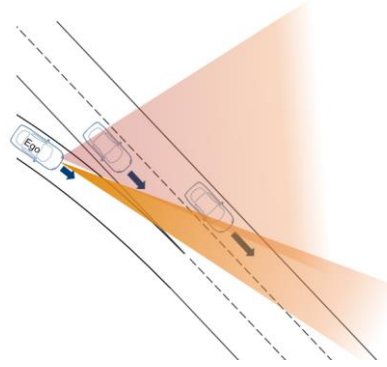
- Enables selected NCAP, AEB and ACC scenarios
- Simulation of targets moving in azimuth, range, radial velocity and target size (RCS)
- Stimulation of a single radar sensor
- Test of front radars in scenarios like Automatic Emergency Braking, Adaptive Cruise Control, ...
- Up to 1 target
- 39° Field-of-View @ 50cm airgap

Frontend	#	Backend	#	Switch	#
QAT100	1	AREG800A	1	OSP220	-
B21 (MIMO)	1	B9 (Digital)	1	B128.3	-
B5 (ASDL)	-	K570 (2 <sup>nd</sup> IF)	-		
		B63 (ASDL)	1		
		K814	1		



# EXEMPLARY DRIVING SCENARIOS

## ADVANCED INSTRUMENT CONFIGURATIONS



### Application:

- Enables selected NCAP, AEB and ACC scenarios
- Simulation of targets moving in azimuth, range, radial velocity and target size (RCS)
- Stimulation of multiple radar sensors
- Test of front and corner radars in scenarios like urban intersections, Highway Construction sites, ...
- Up to 8 targets
- 117° Field-of-View @ 50cm airgap

Frontend	#	Backend	#	Switch	#
QAT100	3	AREG800A	1	OSP220	2
B21 (MIMO)	3	B9 (Digital)	4	B128.3	4
B5 (ASDL)	-	K570 (2 <sup>nd</sup> IF)	4		
		B63 (ASDL)	-		
		K814	4		

# HARDWARE-IN-THE-LOOP COMPONENT TEST

PARTNERSHIP WITH VECTOR



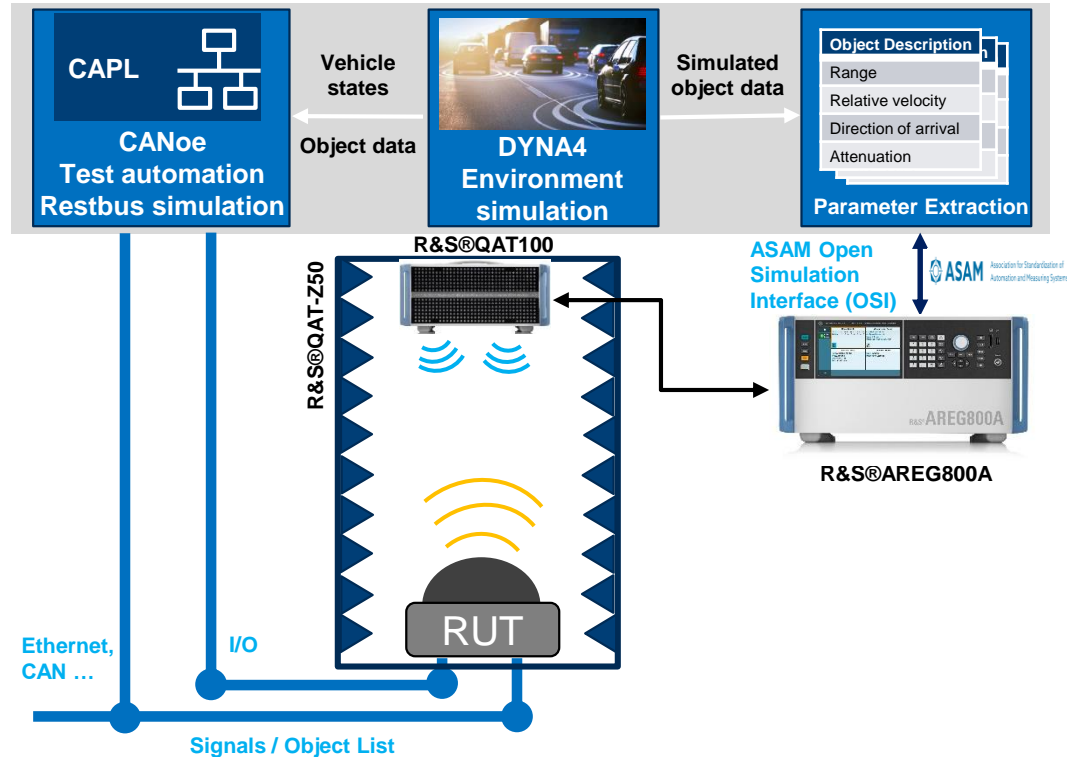
Closed-loop radar module component validation using realistic road scenarios or artificial test cases



CANoe for test automation and restbus simulation via CAN / Ethernet in real-time



Environment simulation via DYNA4 (optional)



# HARDWARE-IN-THE-LOOP INTEGRATION TEST

PARTNERSHIP WITH IPG



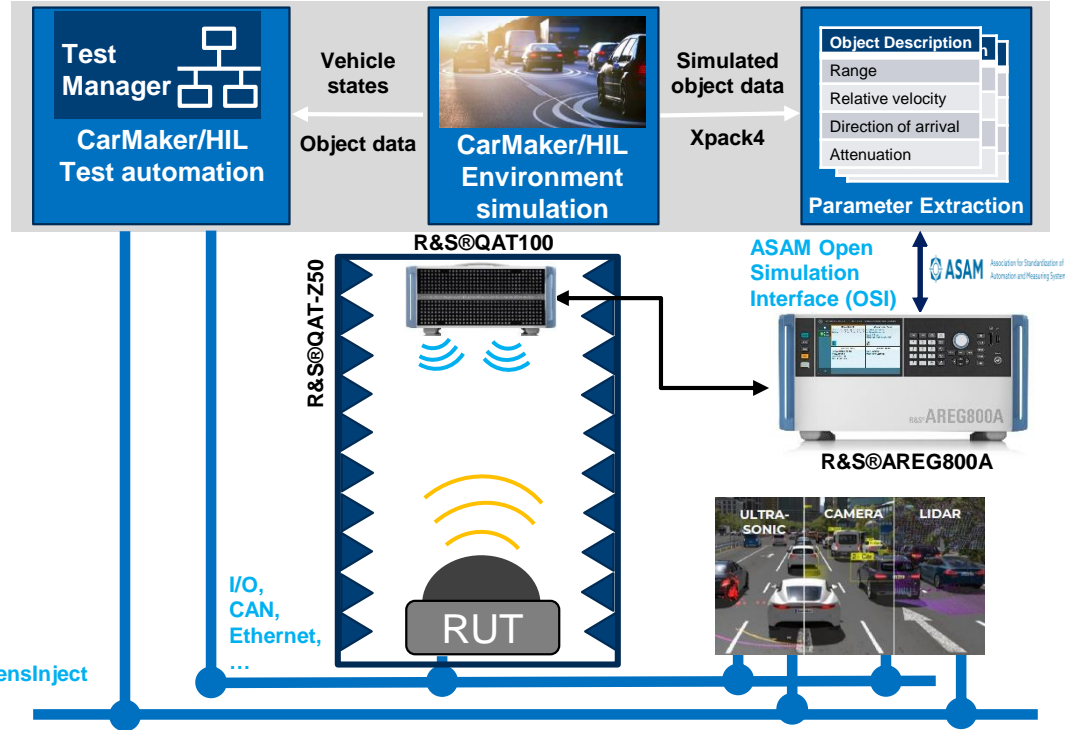
Closed-loop integration test / validation using realistic road scenarios or artificial test cases



Test automation via TestManager (IPG) or ECU-Test (TraceTronic) or EXAM (MicroNova)



Environment simulation via CarMaker (IPG)



# VEHICLE-IN-THE-LOOP VALIDATION

## PARTNERSHIP WITH AVL



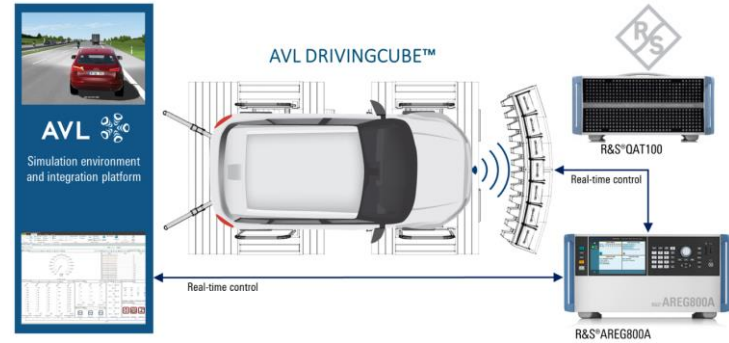
**Closed-loop vehicle validation using realistic road scenarios or artificial test cases**



**Test automation via PUMA**



**Environment simulation via Model.CONNECT using various tools using e.g. VTD, CarMaker, CarSim**







# R&S AUTOMOTIVE RADAR TEST SYSTEM

R&S®QAT100 + R&S®AREG800A



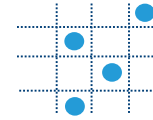
**Azimuth and elevation  
simulation  
without mechanical movement  
& immune to vibration**



**Extremely short distances  
precise and repeatable**



**4GHz instantaneous bandwidth  
across scalable FOV**



**Multiple independent  
dynamic objects**



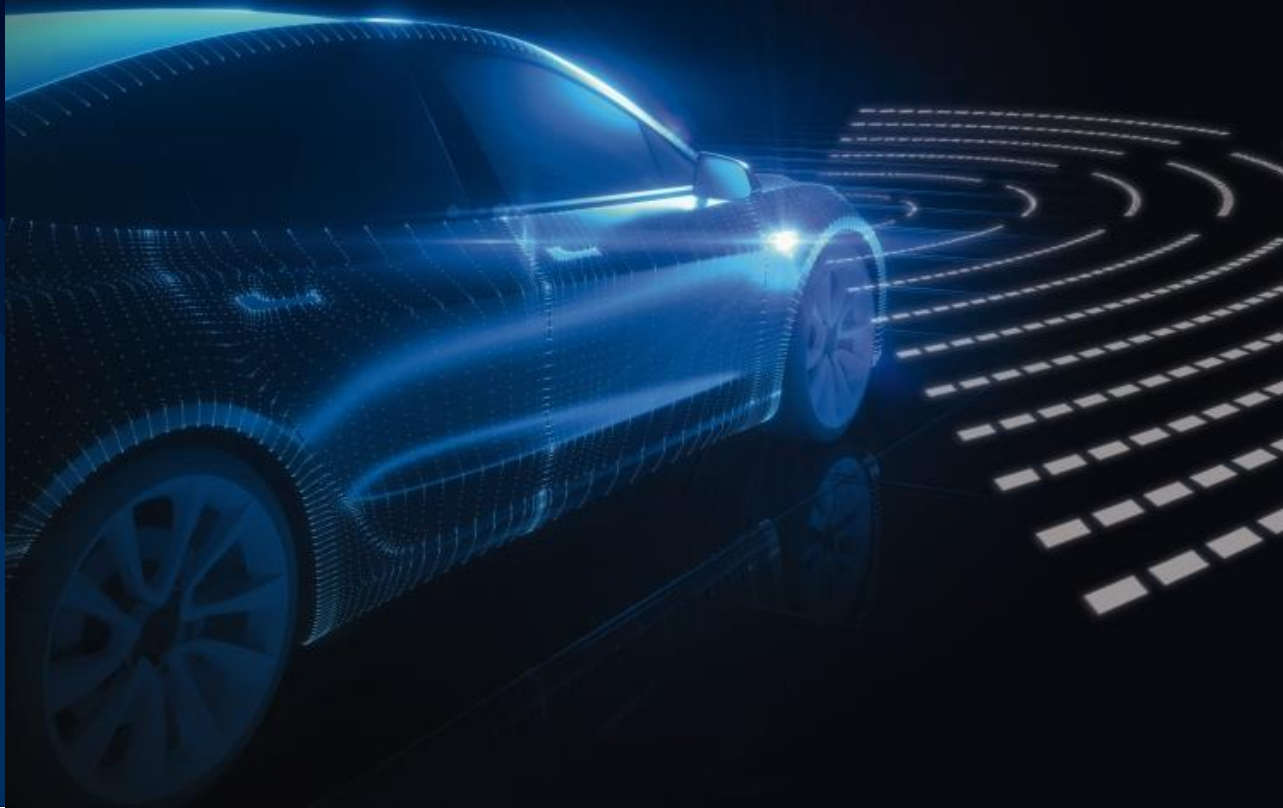
**HiL interface via Open  
Simulation Interface**



**Performance  
optimized system**

# AGENDA

- ▶ Automotive radar technology and market update
- ▶ QAT100 Electronically steerable antenna array
- ▶ AREG800A advanced automotive radar echo generator
- ▶ Applications and solutions
- ▶ **Automotive radar testing product portfolio**
- ▶ Summary and learnings



# RADAR BASED AUTONOMOUS DRIVING

## COMPREHENSIVE TEST AND MEASUREMENT PORTFOLIO FROM R&S



Characterization at  
Chip Suppliers / TIER1s



Validation at  
TIER1s / OEMs



Radome/bumper test in  
R&D and production at  
TIERxs / OEMs

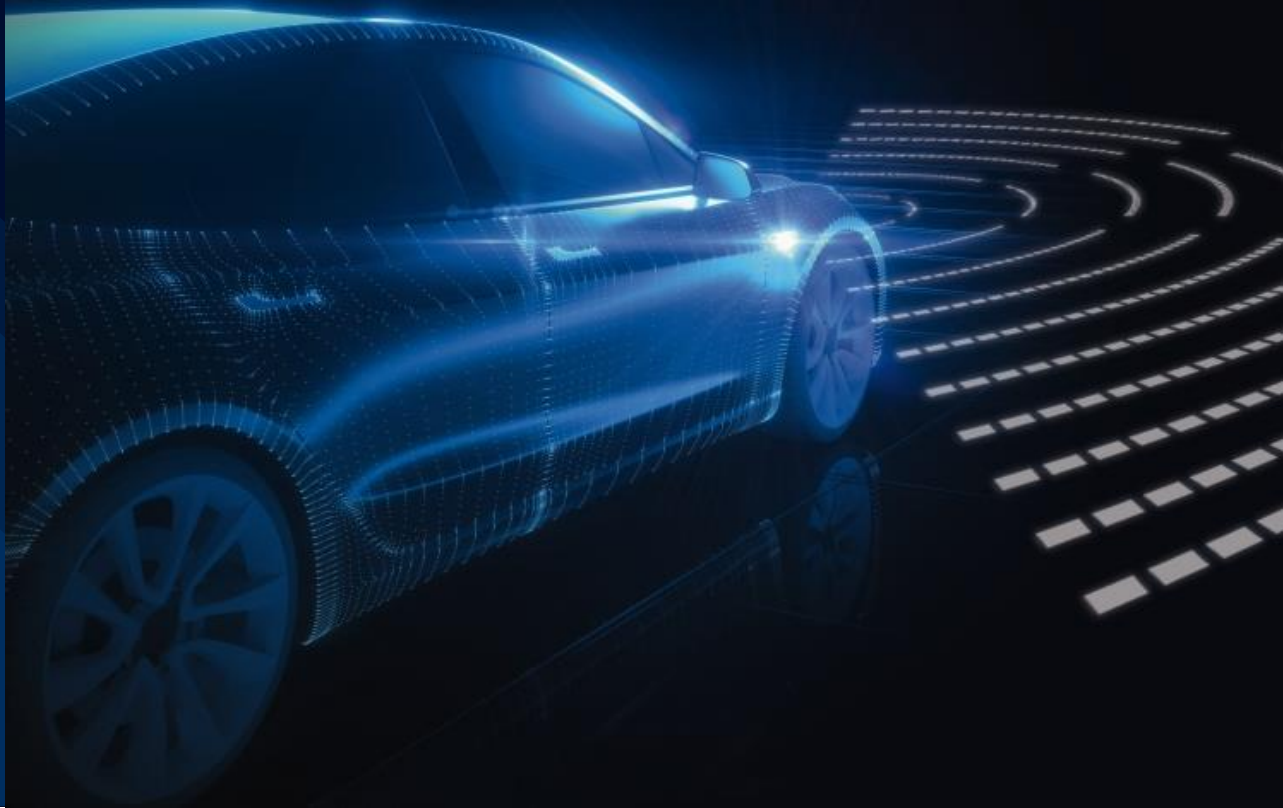


Production test at  
TIER1s



# AGENDA

- ▶ Automotive radar technology and market update
- ▶ QAT100 Electronically steerable antenna array
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- ▶ Applications and solutions
- ▶ Automotive radar testing product portfolio
- ▶ **Summary and learnings**



# SUMMARY AND LEARNINGS

- **Realization of higher levels of ADAS is driving up number and complexity of automotive radars**
  - **Higher bandwidth, complex modulation, MIMO, virtual aperture**
- **5/6th generation radar sensors enter market (trend to single chip CMOS, 5GHz bandwidth) with more complex modulation**
- **Need for complex moving object scenarios to be emulated in a lab environment is increasing**
- **Very short distance object simulation required during radar sensor R&D and validation – addressed with the R&S®AREG800**
- **Future increased testing requirements at functional and ADAS application level – a perfect fit for the very powerful and scalable R&S Radar Test System**





**THANK YOU!**

Find out more: [www.rohde-schwarz.com/automotive/radar](http://www.rohde-schwarz.com/automotive/radar)