

ANALYZING POWER DESIGNS FOR HIGH-SPEED SOCS WITH MULTI-PHASE BUCK CONVERTERS

Martin Stumpf

R&S Segment Manager, Digital Design Test

Juergen Neuhaeusler

TI, Senior Application Engineer

Korbinian Schmidt-Sommerfeld R&S Application Engineer, Oscilloscopes

ROHDE & SCHWARZ

Make ideas real



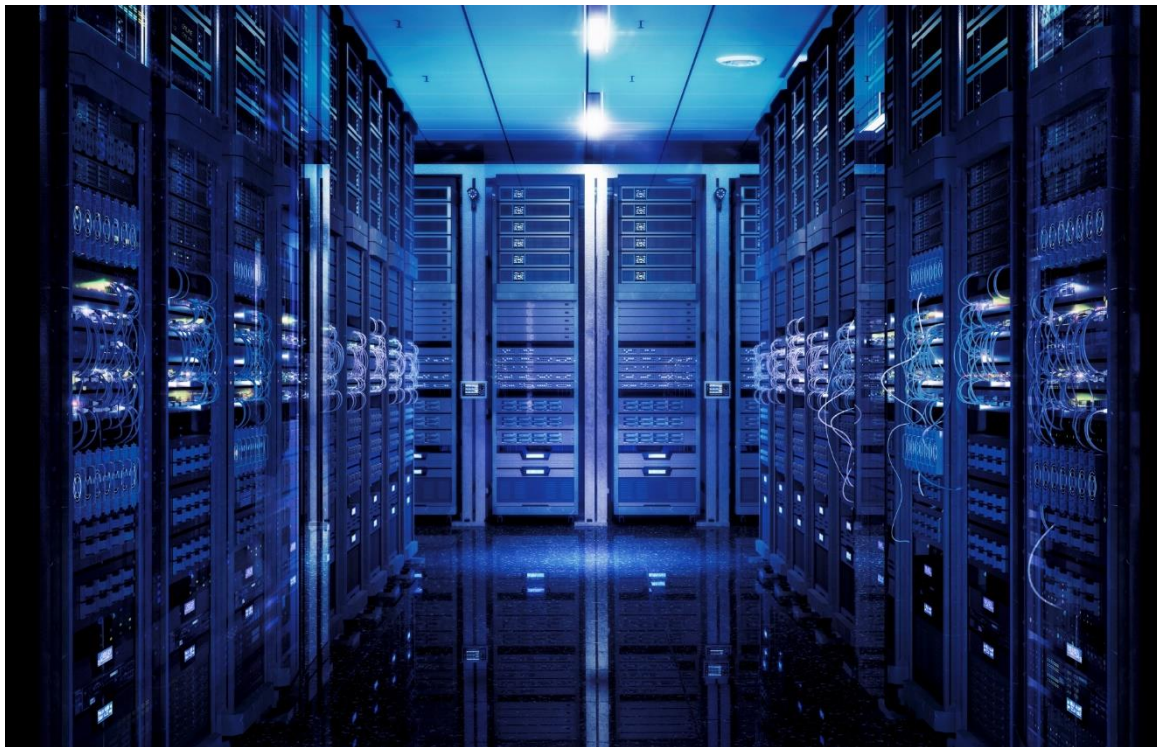
SOC POWER DESIGNS W. MULTI-PHASE BUCK CONVERTERS:

AGENDA:

- INDUSTRY TRENDS
- HOW THEY WORK
- BENEFITS
- IMPLEMENTATIONS
- PERFORMANCE REQUIREMENTS
- VALIDATION AND DEBUG
- TESTING ASPECTS



INCREASING POWER CONSUMPTION OF HIGH-SPEED SOCS: BIG DATA AND ARTIFICIAL INTELLIGENCE



Increasing requirements regarding

- ▶ processing power
- ▶ I/O data rates
- ▶ power efficiency

Decreasing supply voltages with tighter tolerances

- ▶ fast response on load transients
- ▶ low ripple / noise

Increasing supply currents

INCREASING POWER CONSUMPTION OF HIGH-SPEED SOCS: VEHICLE ARCHITECTURE AND AUTONOMOUS DRIVING



Increase of complexity inside the various functional domains

- ▶ ADAS
- ▶ Infotainment
- ▶ Powertrain
- ▶ ...

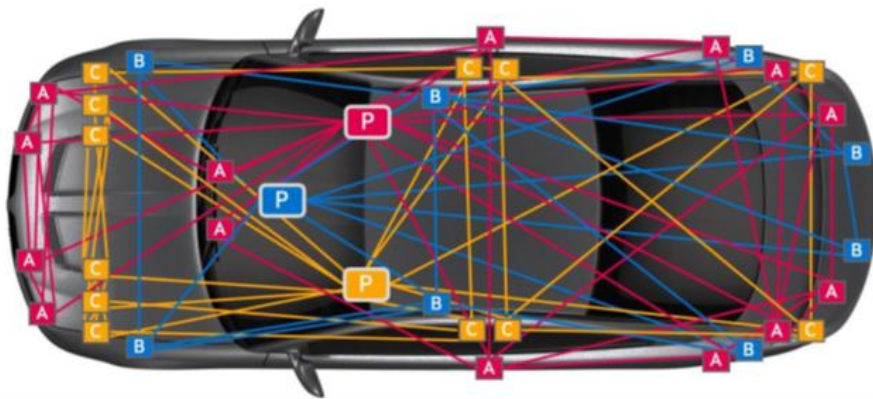
Shift of electronic vehicle architecture

- ▶ from decentralized electronic architecture (multiple, distributed ECUs)
- ▶ towards domain-based architecture with powerful domain controllers and gateways
- ▶ towards centralized architecture with powerful zone controllers and high-speed central computing

INCREASING POWER CONSUMPTION OF HIGH-SPEED SOCS: VEHICLE ARCHITECTURE AND AUTONOMOUS DRIVING

Domain architecture

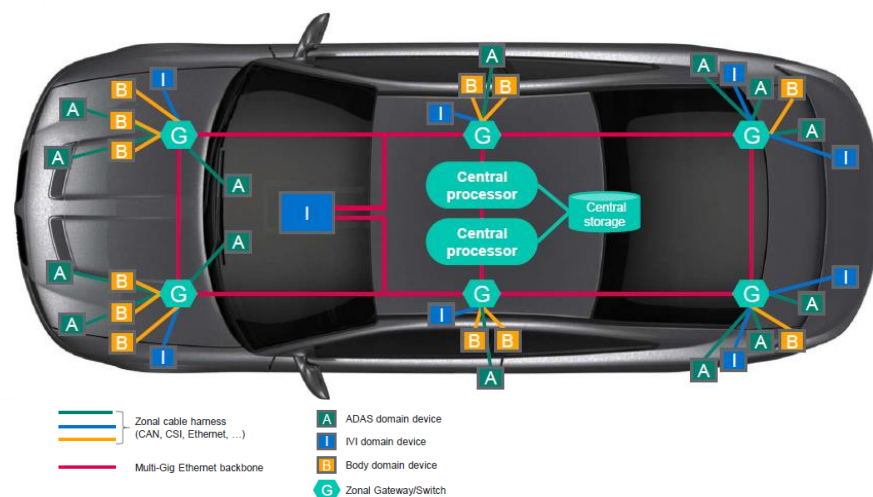
- Central domain controller/high performance computer
- Ability to handle more complex functions
- Consolidation of functions (cost optimization)
- But: cable harness is rigid and expensive



Source: Marvell Automotive Ethernet Congress 2022

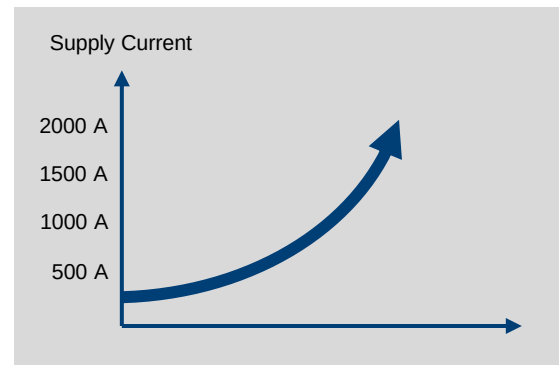
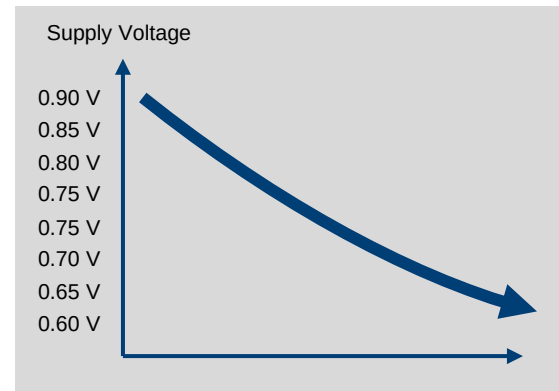
Zonal architecture

- Local ethernet gateway per zone
- Ultra high-speed secured backbone between zones
- Centralized SW
- Central computing & storage

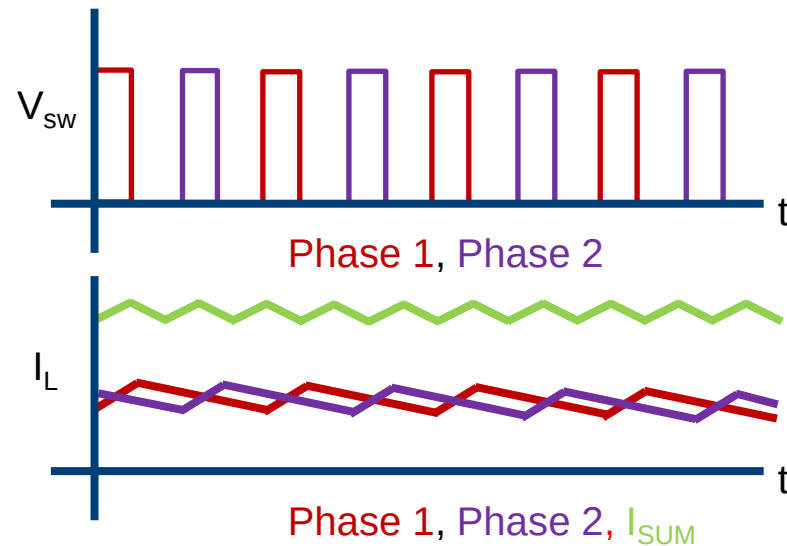
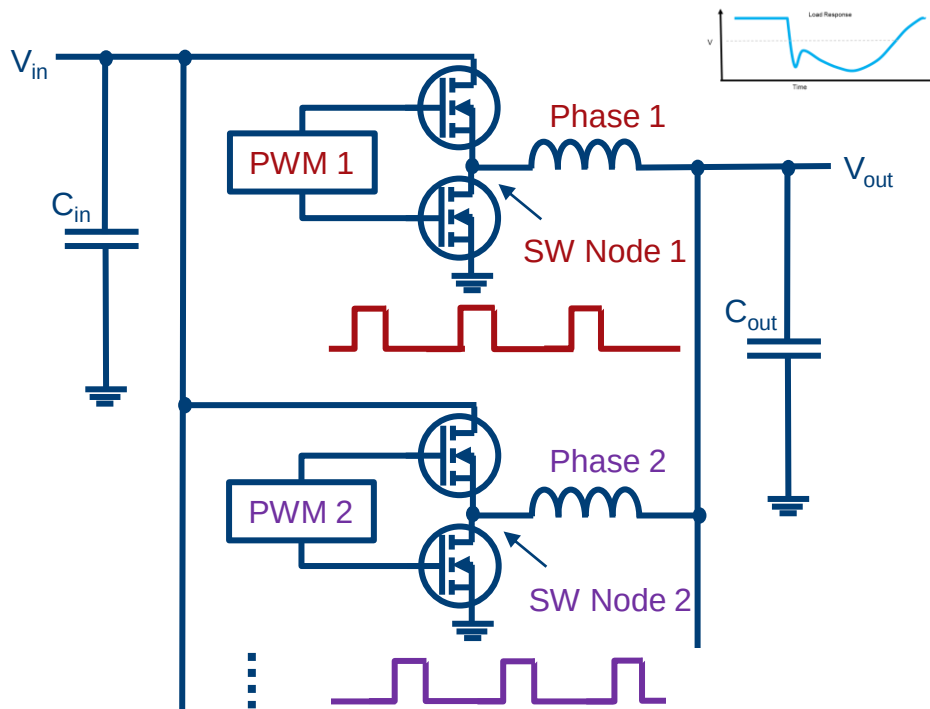


POWER MANAGEMENT FOR SOCS AND RFSOCS: INDUSTRY TRENDS AND CHALLENGES

- ▶ Growing demand of high-performance SoCs and RFSocS in
 - data centers
 - fixed and wireless network infrastructure
 - automotive
 - aerospace / defense
- ▶ Power delivery solutions need to provide a high number of low-voltage power rails with
 - precise sequencing for power-up / power-down
 - high currents on core power rails
 - fast response on load transients, low ripple / noise
 - high efficiency
- ▶ Increasing use of multi-phase buck converters to supply core power rails

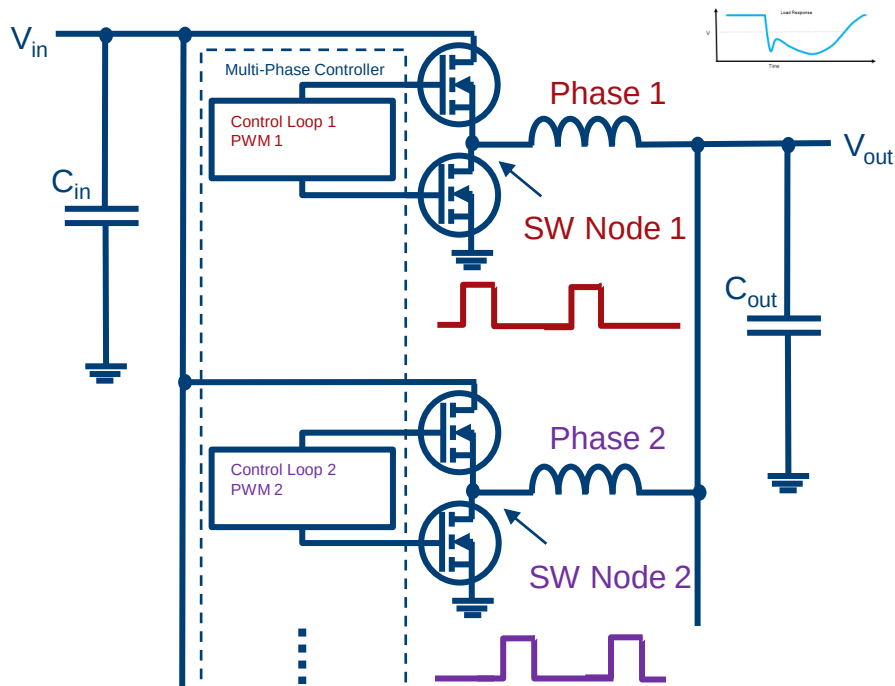


SOC POWER DESIGNS W. MULTI-PHASE BUCK CONVERTERS: FUNCTIONAL PRINCIPLE AND BENEFITS

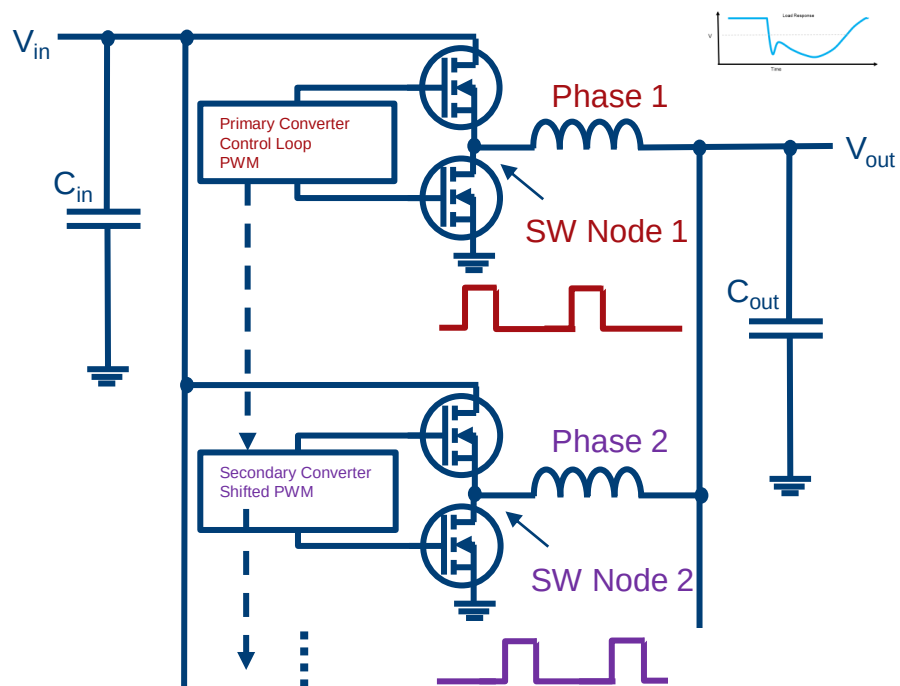


SOC POWER DESIGNS W. MULTI-PHASE BUCK CONVERTERS: FUNCTIONAL PRINCIPLE AND BENEFITS

Design w. Multi-Phase Controller



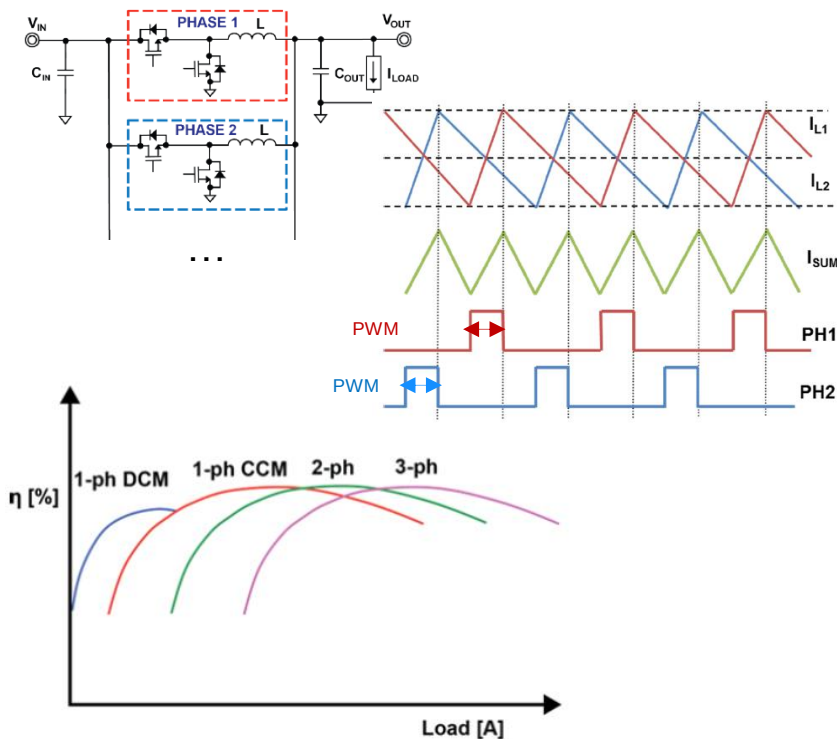
Stacked Design w. Primary and Secondary Converters



SOC POWER DESIGNS W. MULTI-PHASE BUCK CONVERTERS: FUNCTIONAL PRINCIPLE AND BENEFITS

Benefits:

- ▶ reduced voltage ripple (input and output)
→ reduction of input and output capacitance
- ▶ reduced thermal load and improved efficiency in multi-phase mode for high currents
- ▶ flexible phase management to optimize efficiency across a wide range of loads:
 - enabling / disabling of phases
- ▶ improved load transient response time by reaction at next phase after load step and active phase management:
 - load step up: controller overlaps phases
 - load step down: controller turns off phases



Source: Texas Instruments
Application Report: Multiphase Buck Design From Start to Finish (Part 1)

SOC POWER DESIGNS W. MULTI-PHASE BUCK CONVERTERS:

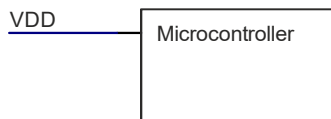
AGENDA:

- INDUSTRY TRENDS
- HOW THEY WORK
- BENEFITS
- IMPLEMENTATIONS
- PERFORMANCE REQUIREMENTS
- VALIDATION AND DEBUG
- TESTING ASPECTS

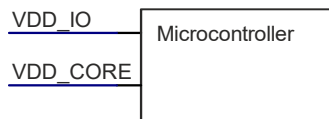


PROCESSOR POWER SUPPLIES

One supply rail
5V or 3.3V
<1A supply current, DC

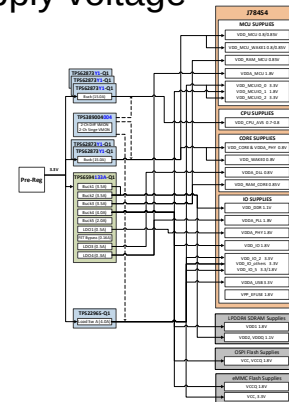
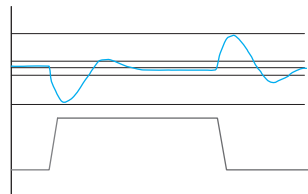


Separate supply rails
for core and I/O
I/O voltage 3.3V or 1.8V
Core voltage 1.8V or below
<10A core supply current
Fast load transients



Multiple supply rails for different functional blocks

- Core voltage <1V
- >10A core supply current
- Fast load transients
- Dynamically adjust supply voltage



LEVELS OF DRIVING AUTOMATION

Level 0

No driving automation



Level 1

Driver assistance

Feet off



Level 2

Partial driving automation

Hands off



Level 3

Conditional driving automation

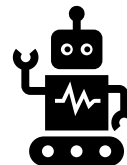
Eyes off



Level 4

High driving automation
Some conditions

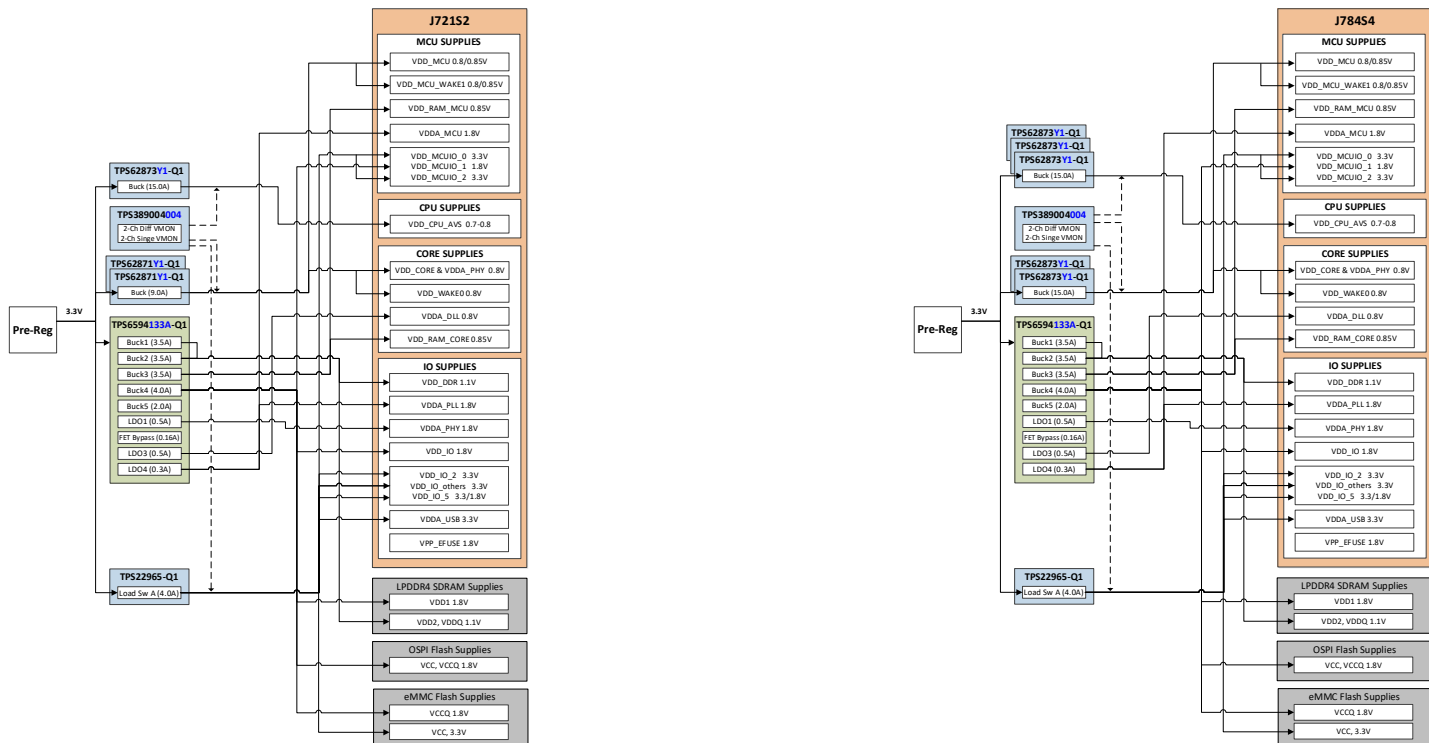
Attention off



Level 5

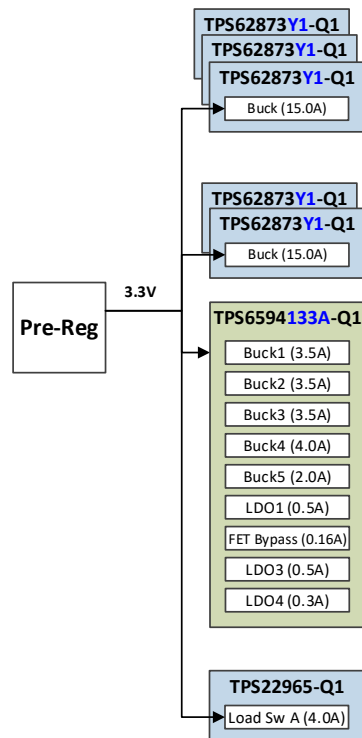
More computation, higher current demand

SOC POWER STRUCTURE - EXAMPLES



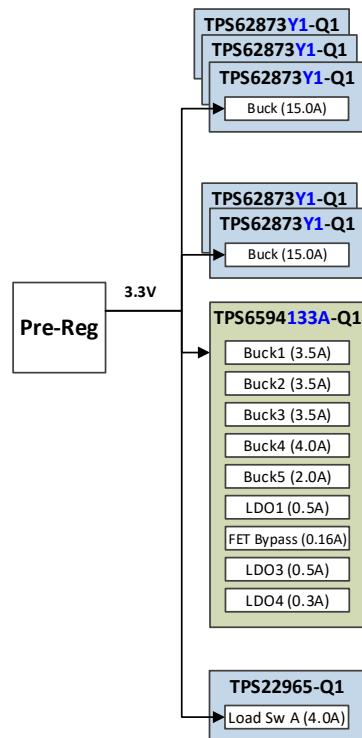
DCDC CONVERTERS IN THE POWER TREE

- ▶ High power section
 - Low voltage core supply
 - High load current variations
 - Dynamically adjust output voltage
- ▶ Lower power section
 - Infrastructure, housekeeping, safety
 - Power up and down sequencing
 - Constant power consumption, on or off



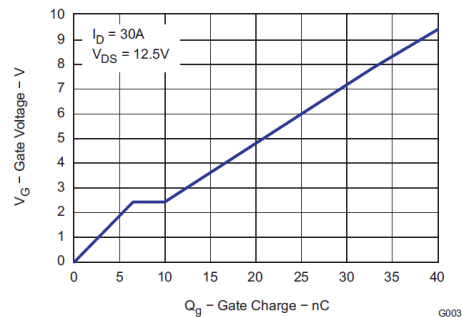
PREREGULATOR FOR HIGH POWER SECTION

- ▶ Filtering towards infrastructure
- ▶ Efficiency improvements
- ▶ Higher switching frequency

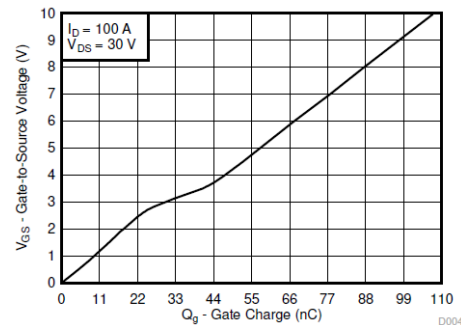


PREREGULATOR FOR HIGH POWER SECTION

V_{DS}	Drain to Source Voltage	25	V
Q_g	Gate Charge Total (4.5 V)	18	nC
Q_{gd}	Gate Charge Gate to Drain	3.5	nC
$R_{DS(on)}$	Drain to Source On Resistance	$V_{GS} = 3\text{ V}$	2.1 m Ω
		$V_{GS} = 4.5\text{ V}$	1.7 m Ω
		$V_{GS} = 8\text{ V}$	1.5 m Ω
$V_{GS(th)}$	Threshold Voltage	1.1	V

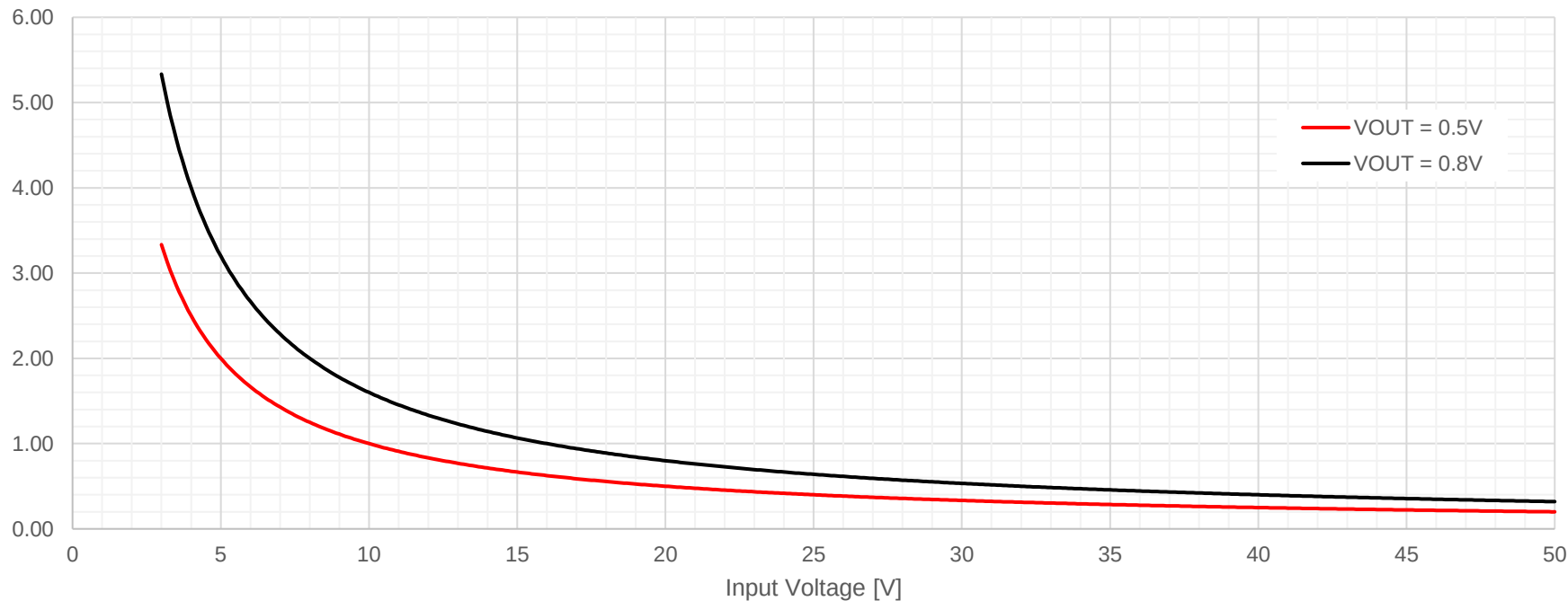


V_{DS}	Drain-to-Source Voltage	60	V
Q_g	Gate Charge Total (10V)	108	nC
Q_{gd}	Gate Charge Gate-to-Drain	14	nC
$R_{DS(on)}$	Drain-to-Source On-Resistance	$V_{GS} = 4.5\text{ V}$	1.7 m Ω
		$V_{GS} = 10\text{ V}$	1.3 m Ω
$V_{GS(th)}$	Threshold Voltage	1.8	V



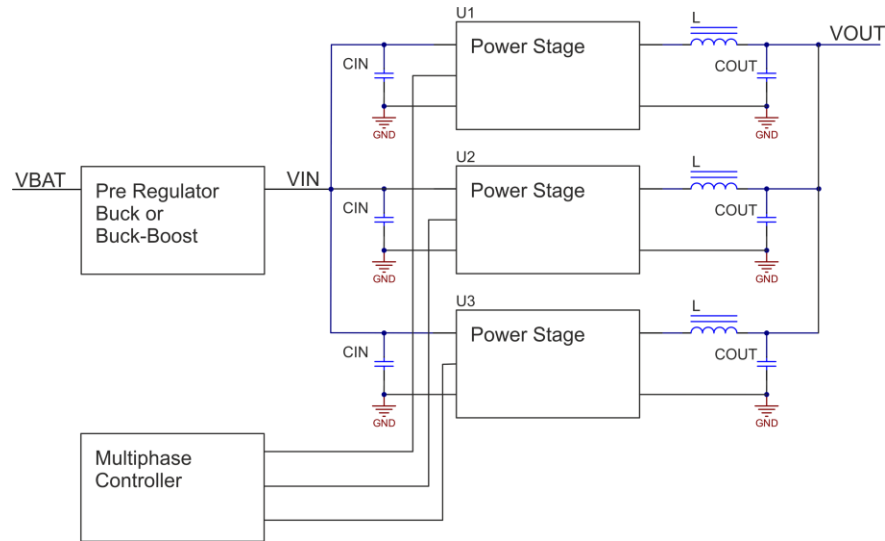
SWITCHING FREQUENCY

Maximum Switching Frequency [MHz]

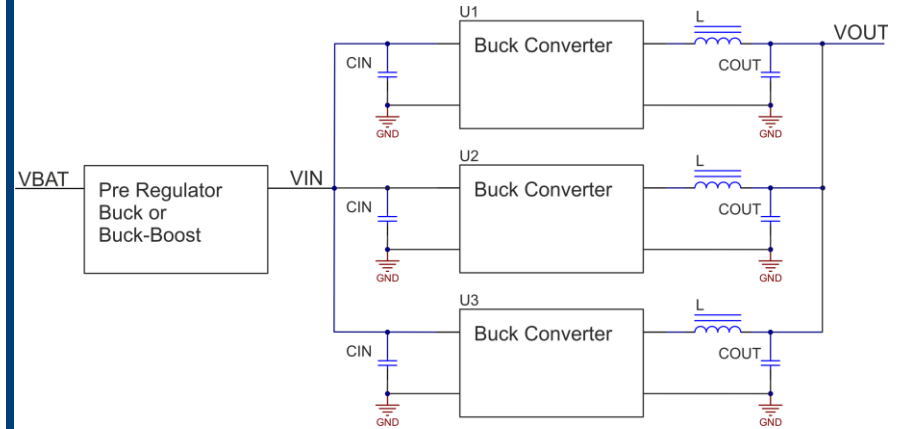


COMPARISON - INPUT TO CORE

Controller based VR power tree

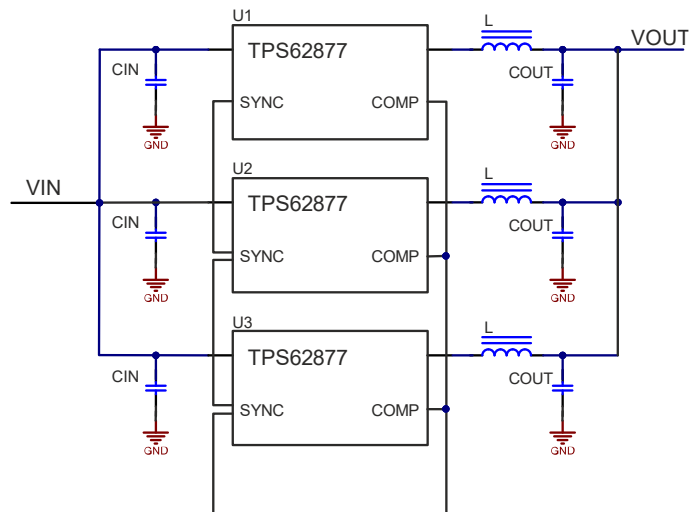


Converter based VR power tree

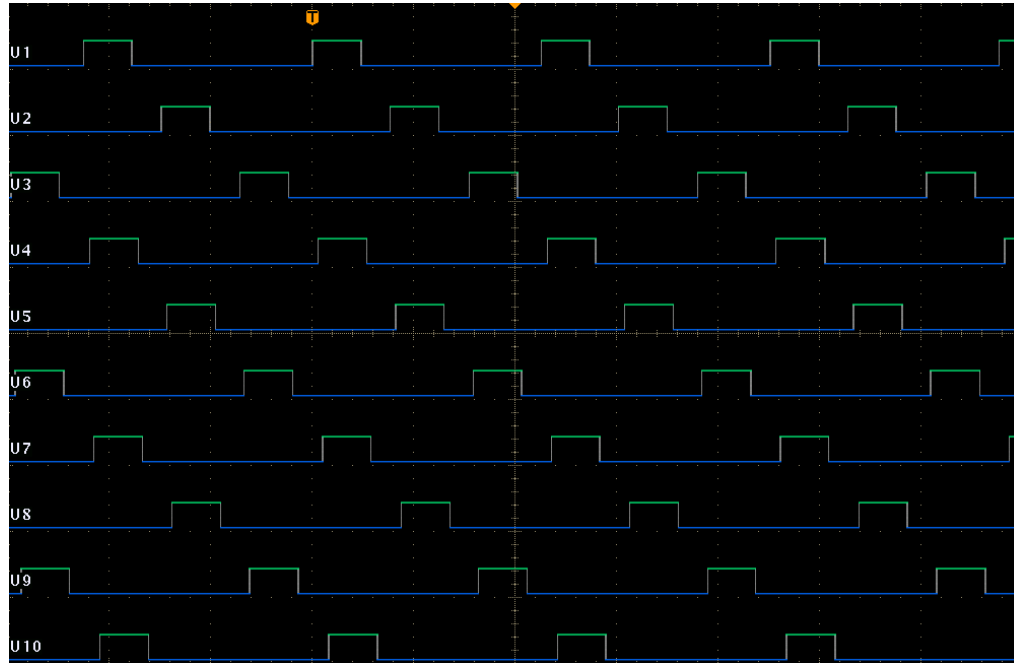


EXAMPLE

- ▶ Supply voltage range 3V to 5V
- ▶ Output voltage 0.8V, +/-3%
- ▶ Maximum continuous output current 300A
- ▶ 10 TPS62877 converters in parallel
 - Synchronized, interleaved operation
 - Primary device senses output differentially
 - Shared COMP signal for current sharing

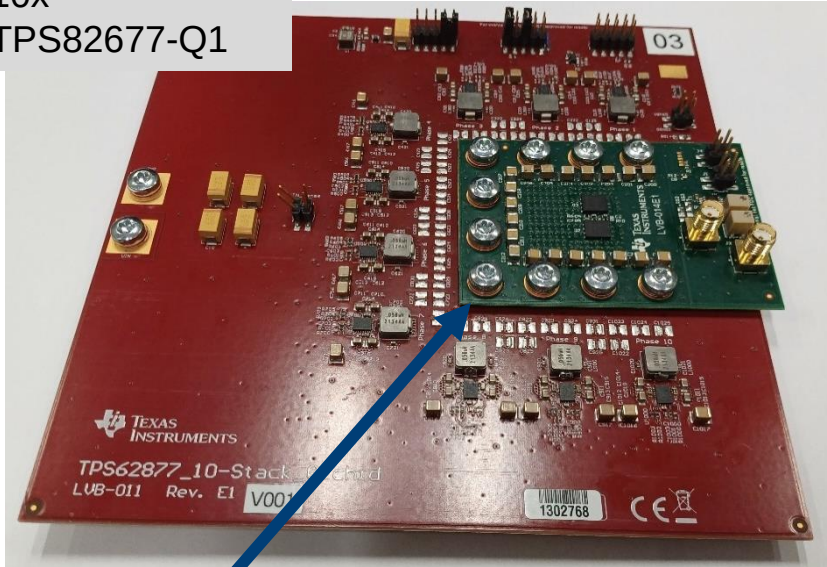


PHASE SHIFTED SYNCHRONIZATION



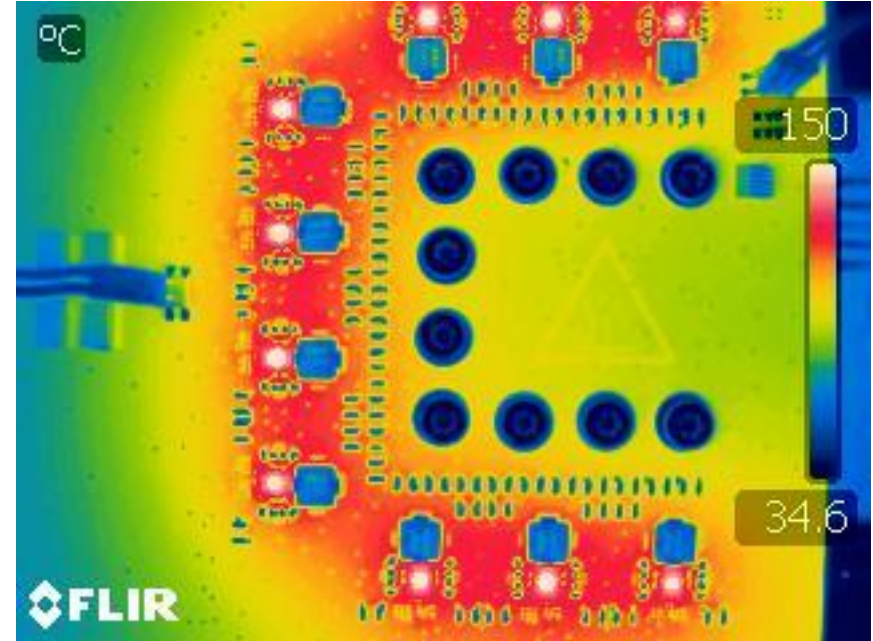
HARDWARE TEST RESULTS

10x
TPS82677-Q1



Load transient test board

Thermal image (3.3V in, 300A out)



HARDWARE TEST RESULTS



SOC POWER DESIGNS W. MULTI-PHASE BUCK CONVERTERS:

AGENDA:

- INDUSTRY TRENDS
- HOW THEY WORK
- BENEFITS
- IMPLEMENTATIONS
- PERFORMANCE REQUIREMENTS
- VALIDATION AND DEBUG
- TESTING ASPECTS



MEASUREMENT CHALLENGES

- Efficiency
- Load step response
- Power integrity
- Bus control signal response
- Feedback loop gain

→ R&S MXO 5 Oscilloscope



MXO5 KEY BENEFITS FOR POWER CONVERTER ANALYSIS

8 analog
+ 16 digital
channels

12-bit ADC 18-bit HD

500 Mpts
memory /ch

Digital trigger

> 45 k
FFT / sec

Standard MSO



Rohde & Schwarz

R&S® PROBES FOR YOUR APPLICATION



Passive

- General purpose
- Extensive accessories
- Up to 700MHz



Power rail

- High sensitivity
- $\pm 60V$ offset
- 2GHz or 4GHz



EMC near field

- E-field probes
- B-field probes
- High spatial resolution



Differential

- High input impedance
- Low input capacity
- Up to 4.5GHz



Current

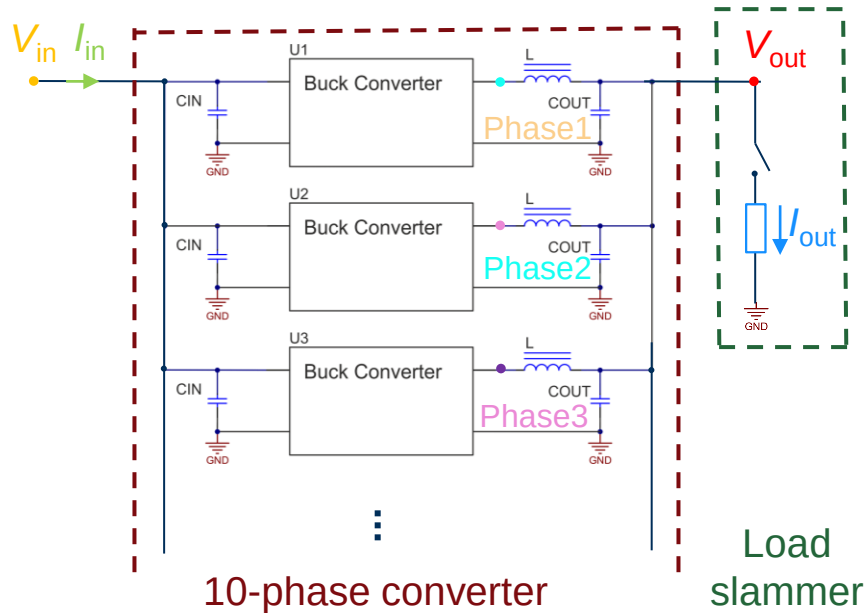
- Non-intrusive
- DC to 120MHz
- Up to 2kA



Logic

- 16 additional digital channels
- 5GSa/s
- Powerful trigger

MEASUREMENT SETUP



Load slammer:

- ▶ 5mΩ load
- ▶ 15μs pulses with 200 Hz
- ▶ Current measurement across load

Measurement points:

- ▶ Input voltage V_{in} & current I_{in}
- ▶ Output voltage V_{out} & current I_{out}
- ▶ Switch nodes of phase 1, phase 2, phase 3 and phase 4
- ▶ Digital channels: phase 5 to 10, I²C signal

EFFICIENCY



Rohde & Schwarz

Analyzing SoC Power Designs with Multi-Phase Buck Converters

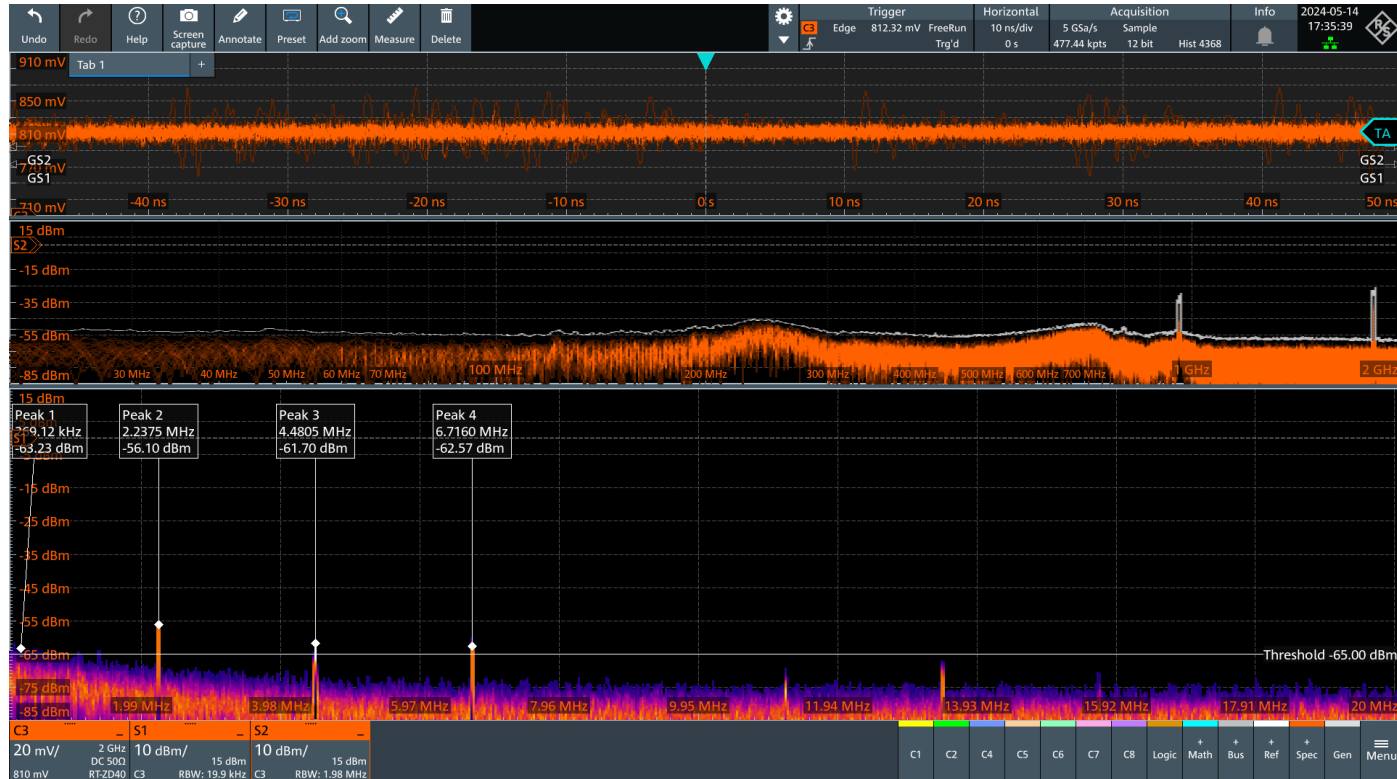
LOAD STEP RESPONSE



VOLTAGE CHANGE RESPONSE TIME



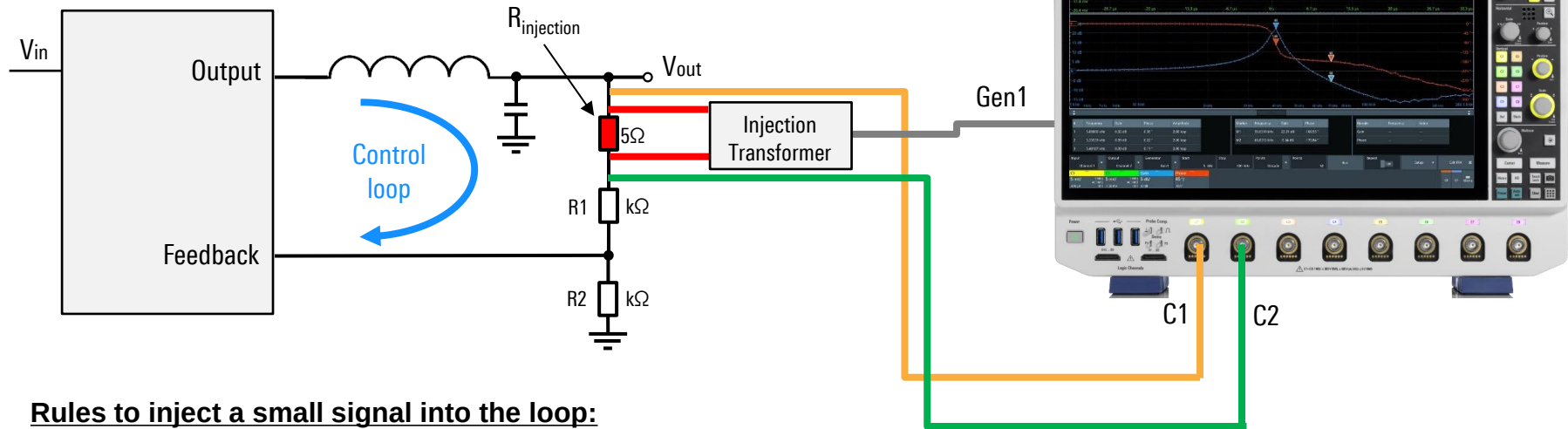
POWER INTEGRITY



Rohde & Schwarz

Analyzing SoC Power Designs with Multi-Phase Buck Converters

CONVERTER STABILITY VERIFICATION



Rules to inject a small signal into the loop:

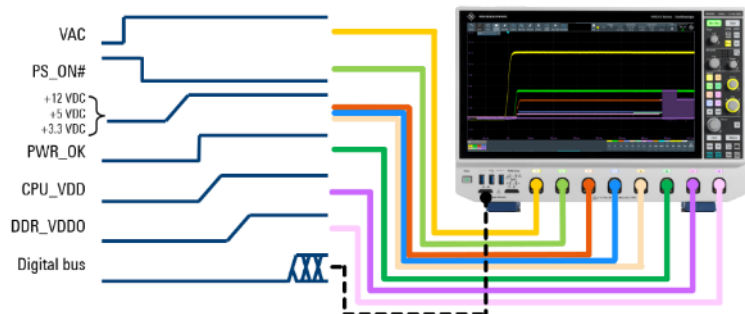
1. Output impedance of the output stage is much lower compared to the input impedance of the feedback loop
2. Ensure that all relevant components which are part of the loop are included

FREQUENCY RESPONSE ANALYSIS FOR CONTROL LOOP RESPONSE



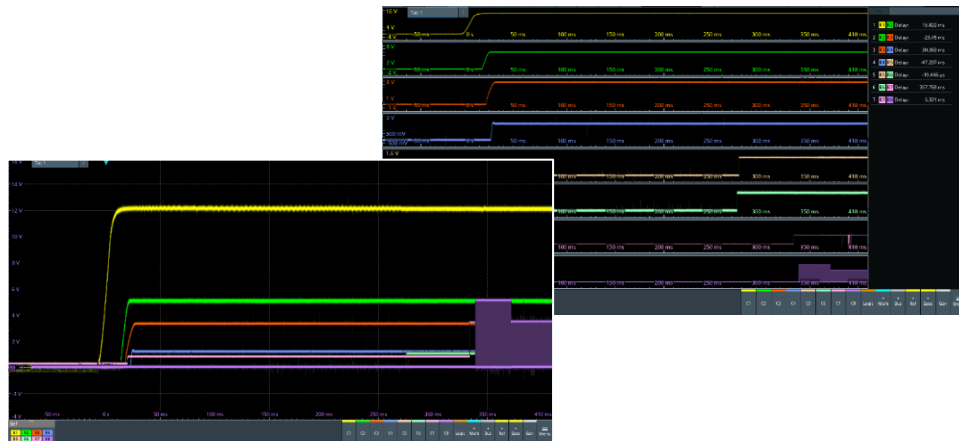
- ▶ Bode plot oscilloscope application
- ▶ 10mHz to 100MHz
- ▶ Custom amplitude profile
- ▶ Result table
- ▶ Cursor analysis
- ▶ Gain & phase margin

VERIFICATION OF POWER SEQUENCING IN POWER DELIVERY DESIGNS WITH MULTIPLE POWER RAILS



- ▶ Multiple channels to see more events
- ▶ Deep record length for longer observations
- ▶ Flexible and intuitive waveform setup
- ▶ Configurable delay measurement setup

Sampling rate	Capture Duration (500 Mpoints)	Capture Duration (1Gpoints)
5 Gsample/s	100 ms	200 ms
500 Msample/s	1 s	2 s
5 Msample/s	100 s	200 s
8 Ksample/s	17h 21m 40s	1d 10h 43m 20s



SOC POWER DESIGNS W. MULTI-PHASE BUCK CONVERTERS:

SUMMARY:

- HIGH POWER DEMAND OF HIGH SPEED SOC
- MULTI-PHASE BUCK CONVERTER FOR HIGH CURRENT SUPPLY
- VARIOUS MEASUREMENTS REQUIRED



Find out more

www.rohde-schwarz.com

www.ti.com

Thank you!

ROHDE & SCHWARZ

Make ideas real

